## ESP-WROOM-32 Datasheet



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## About This Guide

This document provides introduction to the specifications of the ESP-WROOM-32 module.
The document structure is as follows:

| Chapter | Title | Subject |
| :--- | :--- | :--- |
| Chapter 1 | Preface | An overview of ESP-WROOM-32 |
| Chapter 2 | Pin Definitions | Device pinout and pin descriptions |
| Chapter 3 | Functional Description | Description of major functional modules and protocols |
| Chapter 4 | Electrical Characteristics | Electrical characteristics and specifications of ESP-WROOM-32 |
| Chapter 5 | Schematics | The schematics of ESP-WROOM-32 |

## Release Notes

| Date | Version | Release notes |
| :--- | :--- | :--- |
| 2016.08 | V1.0 | First release |
| 2016.11 | V1.1 | Updated Chapter 5 |
| 2016.11 | V1.2 | Added Peripheral Schematics |
| 2016.12 | V1.3 | Updated Chapter 2.1 |

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## Contents

1 Preface ..... 1
2 Pin Definitions ..... 3
2.1 Pin Layout ..... 3
2.2 Pin Description ..... 4
2.3 Strapping Pins ..... 5
3 Functional Description ..... 6
3.1 CPU and Internal Memory ..... 6
3.2 External Flash and SRAM ..... 6
3.3 Crystal Oscillators ..... 6
3.4 Power Consumption ..... 7
3.5 Peripherals and Sensors ..... 8
3.5.1 Peripherals and Sensors Description ..... 8
3.5.2 Peripheral Schematics ..... 13
4 Electrical Characteristics ..... 14
4.1 Absolute Maximum Ratings ..... 14
4.2 Recommended Operating Conditions ..... 14
4.3 Digital Terminal Characteristics ..... 14
4.4 Wi-Fi Radio ..... 15
4.5 Bluetooth LE Radio ..... 15
4.5.1 Receiver ..... 15
4.5.2 Transmit ..... 16
4.6 Reflow Profile ..... 16
5 Schematics ..... 17

## List of Tables

1 ESP-WROOM-32 Specifications 2
2 ESP-WROOM-32 Dimensions 3
3 ESP-WROOM-32 Pin Definitions 4
4 Strapping Pins 5
5 Power Consumption by Power Modes 7
6 Peripherals and Sensors Description 8
7 Absolute Maximum Ratings 14
8 Recommended Operating Conditions 14
9 Digital Terminal Characteristics 14
10 Wi-Fi Radio Characteristics 15
11 Receiver Characteristics - BLE 15
12 Transmit Characteristics - BLE 16
13 Reflow Profile 16

## List of Figures

1 Top and Side View of ESP-WROOM-32 3
2 ESP-WROOM-32 Peripheral Schematics 13
3 ESP-WROOM-32 Schematics 17

## 1. Preface

ESP-WROOM-32 is a powerful, generic WiFi-BT-BLE MCU module that targets a wide variety of applications, ranging from low-power sensor networks to the most demanding tasks, such as voice encoding, music streaming and MP3 decoding.

At the core of this module is the ESP32 chip, which is designed to be scalable and adaptive. There are 2 CPU cores that can be individually controlled or powered, and the clock frequency is adjustable from 80 MHz to 240 MHz . The user may also power off the CPU and make use of the low-power coprocessor to constantly monitor the peripherals for changes or crossing of thresholds. ESP32 integrates a rich set of peripherals, ranging from capacitive touch sensors, Hall sensors, low-noise sense amplifiers, SD card interface, Ethernet, high speed SDIO/SPI, UART, I2S and I 2 C .

The integration of Bluetooth, Bluetooth LE and Wi-Fi ensures that a wide range of applications can be targeted, and that the module is future proof: using Wi-Fi allows a large physical range and direct connection to the internet through a Wi-Fi router, while using Bluetooth allows the user to conveniently connect to the phone or broadcast low energy beacons for its detection. The sleep current of the ESP32 chip is less than $5 \mu \mathrm{~A}$, making it suitable for battery powered and wearable electronics applications. ESP-WROOM-32 supports data rates of up to 150 Mbps, and 22 dBm output power at the PA to ensure the widest physical range. As such the chip does offer industry-leading specifications and the best performance for electronic integration, range, power consumption, and connectivity.

The operating system chosen for ESP32 is freeRTOS with LWIP; TLS 1.2 with hardware acceleration is built in as well. Secure (encrypted) over the air (OTA) upgrade is also supported, so that developers can continually upgrade their products even after their release.

Table 1 provides the specifications of ESP-WROOM-32.

Table 1: ESP-WROOM-32 Specifications

| Categories | Items | Specifications |
| :---: | :---: | :---: |
| Wi-Fi | Standards | FCC/CE/IC/TELEC/KCC/SRRC/NCC |
|  |  | $802.11 \mathrm{~b} / \mathrm{g} / \mathrm{n} / \mathrm{d} / \mathrm{e} / \mathrm{i} / \mathrm{k} / \mathrm{r}$ (802.11n up to 150 Mbps ) |
|  | Protocols | A-MPDU and A-MSDU aggregation and $0.4 \mu \mathrm{~s}$ guard interval support |
|  | Frequency range | $2.4 \sim 2.5 \mathrm{GHz}$ |
| Bluetooth | Protocols | Bluetooth v4.2 BR/EDR and BLE specification |
|  | Radio | NZIF receiver with -98 dBm sensitivity |
|  |  | Class-1, class-2 and class-3 transmitter |
|  |  | AFH |
|  | Audio | CVSD and SBC |
| Hardware | Module interface | SD card, UART, SPI, SDIO, I2C, LED PWM, Motor PWM, I2S, I2C, IR |
|  |  | GPIO, capacitive touch sensor, ADC, DAC, LNA pre-amplier |
|  | On-chip sensor | Hall sensor, temperature sensor |
|  | On-board clock | 26 MHz crystal, 32 kHz crystal |
|  | Operating voltage | 2.2 ~ 3.6V |
|  | Operating current | Average: 80 mA |
|  | Operating temperature range | $-40^{\circ} \mathrm{C} \sim 85^{\circ} \mathrm{C}$ * |
|  | Ambient temperature range | Normal temperature |
|  | Package size | $18 \mathrm{~mm} \times 25.5 \mathrm{~mm} \times 2.8 \mathrm{~mm}$ |
| Software | Wi-Fi mode | Station/softAP/SoftAP+station/P2P |
|  | Security | WPAWPA2/WPA2-Enterprise/WPS |
|  | Encryption | AES/RSA/ECC/SHA |
|  | Firmware upgrade | UART Download / OTA (via network) / download and write firmware via host |
|  | Software development | Supports Cloud Server Development / SDK for custom firmware development |
|  | Network protocols | IPv4, IPv6, SSL, TCP/UDP/HTTP/FTP/MQTT |
|  | User configuration | AT instruction set, cloud server, Android/iOS App |

## Note:

* ESP-WROOM-32 with the industry-standard temperature range $\left(-40^{\circ} \mathrm{C} \sim 125^{\circ} \mathrm{C}\right)$ is available for custom order.


## 2. Pin Definitions

### 2.1 Pin Layout



Figure 1: Top and Side View of ESP-WROOM-32

Table 2: ESP-WROOM-32 Dimensions

| Length | Width | Height | PAD size (bottom) | Pin pitch | Shielding can height | PCB thickness |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 18 mm | 25.5 mm | $2.8 \pm 0.1 \mathrm{~mm}$ | $0.45 \mathrm{~mm} \times 0.9 \mathrm{~mm}$ | 1.27 mm | 2 mm | $0.8 \pm 0.1 \mathrm{~mm}$ |

### 2.2 Pin Description

ESP-WROOM-32 has 38 pins. See pin definitions in Table 3.
Table 3: ESP-WROOM-32 Pin Definitions

| Name | No. | Function |
| :---: | :---: | :---: |
| GND | 1 | Ground |
| 3V3 | 2 | Power supply. |
| EN | 3 | Chip-enable signal. Active high. |
| SENSOR_VP | 4 | GPI36, SENSOR_VP, ADC_H, ADC1_CH0, RTC_GPIOO |
| SENSOR_VN | 5 | GPI39, SENSOR_VN, ADC1_CH3, ADC_H, RTC_GPIO3 |
| IO34 | 6 | GPI34, ADC1_CH6, RTC_GPIO4 |
| 1035 | 7 | GPI35, ADC1_CH7, RTC_GPIO5 |
| IO32 | 8 | GPIO32, XTAL_32K_P (32.768 kHz crystal oscillator input), ADC1_CH4, TOUCH9, RTC_GPIO9 |
| 1033 | 9 | GPIO33, XTAL_32K_N (32.768 kHz crystal oscillator output), ADC1_CH5, TOUCH8, RTC_GPIO8 |
| IO25 | 10 | GPIO25, DAC_1, ADC2_CH8, RTC_GPIO6, EMAC_RXD0 |
| 1 O 26 | 11 | GPIO26, DAC_2, ADC2_CH9, RTC_GPIO7, EMAC_RXD1 |
| IO27 | 12 | GPIO27, ADC2_CH7, TOUCH7, RTC_GPIO17, EMAC_RX_DV |
| 1014 | 13 | GPIO14, ADC2_CH6, TOUCH6, RTC_GPIO16, MTMS, HSPICLK, HS2_CLK, SD_CLK, EMAC_TXD2 |
| 1012 | 14 | GPIO12, ADC2_CH5, TOUCH5, RTC_GPIO15, MTDI, HSPIQ, HS2_DATA2, SD_DATA2, EMAC_TXD3 |
| GND | 15 | Ground |
| 1013 | 16 | GPIO13, ADC2_CH4, TOUCH4, RTC_GPIO14, MTCK, HSPID, HS2_DATA3, SD_DATA3, EMAC_RX_ER |
| SHD/SD2 | 17 | GPIO9, SD_DATA2, SPIHD, HS1_DATA2, U1RXD |
| SWP/SD3 | 18 | GPIO10, SD_DATA3, SPIWP, HS1_DATA3, U1TXD |
| SCS/CMD | 19 | GPIO11, SD_CMD, SPICS0, HS1_CMD, U1RTS |
| SCK/CLK | 20 | GPIO6, SD_CLK, SPICLK, HS1_CLK, U1CTS |
| SDO/SD0 | 21 | GPIO7, SD_DATA0, SPIQ, HS1_DATA0, U2RTS |
| SDI/SD1 | 22 | GPIO8, SD_DATA1, SPID, HS1_DATA1, U2CTS |
| 1015 | 23 | GPIO15, ADC2_CH3, TOUCH3, MTDO, HSPICSO, RTC_GPIO13, HS2_CMD, SD_CMD, EMAC_RXD3 |
| IO2 | 24 | ```GPIO2, ADC2_CH2, TOUCH2, RTC_GPIO12, HSPIWP, HS2_DATAO, SD_DATAO``` |
| 100 | 25 | GPIO0, ADC2_CH1, TOUCH1, RTC_GPIO11, CLK_OUT1, EMAC_TX_CLK |
| IO4 | 26 | GPIO4, ADC2_CHO, TOUCHO, RTC_GPIO10, HSPIHD, HS2_DATA1, SD_DATA1, EMAC_TX_ER |
| 1016 | 27 | GPIO16, HS1_DATA4, U2RXD, EMAC_CLK_OUT |
| 1017 | 28 | GPIO17, HS1_DATA5, U2TXD, EMAC_CLK_OUT_180 |
| IO5 | 29 | GPIO5, VSPICS0, HS1_DATA6, EMAC_RX_CLK |
| 1018 | 30 | GPIO18, VSPICLK, HS1_DATA7 |
| 1019 | 31 | GPIO19, VSPIQ, U0CTS, EMAC_TXD0 |
| NC | 32 | - |


| Name | No. | Function |
| :--- | :--- | :--- |
| IO21 | 33 | GPIO21, VSPIHD, EMAC_TX_EN |
| RXD0 | 34 | GPIO3, UORXD, CLK_OUT2 |
| TXD0 | 35 | GPIO1, UOTXD, CLK_OUT3, EMAC_RXD2 |
| IO22 | 36 | GPIO22, VSPIWP, UORTS, EMAC_TXD1 |
| IO23 | 37 | GPIO23, VSPID, HS1_STROBE |
| GND | 38 | Ground |

### 2.3 Strapping Pins

ESP32 has five strapping pins. Software can read the value of these five bits from the register "GPIO_STRAPPING". During the chip power-on reset, the latches of the strapping pins sample the voltage level as strapping bits of "0" or "1", and hold these bits until the chip is powered down or shut down.

Each strapping pin is connected with its internal pull-up/pull-down during the chip reset. Consequently, if a strapping pin is unconnected or the connected external circuit is high-impendence, the internal weak pull-up/pull-down will determine the default input level of the strapping pins.

To change the strapping bit values, users can apply the external pull-down/pull-up resistances, or apply the host MCU's GPIOs to control the voltage level of these pins when powering ESP32 on.

After reset, the strapping pins work as the normal functions pins.
Refer to Table 4 for detailed boot modes of configuration by strapping pins.
Table 4: Strapping Pins

| Voltage of Internal LDO (VDD_SDIO) |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Pin | Default | 3.3 V |  | 1.8 V |  |
| MTDI | Pull-down | 0 |  | 1 |  |
| Booting Mode |  |  |  |  |  |
| Pin | Default | SPI Flash Boot |  | Download Boot |  |
| GPIO0 | Pull-up | 1 |  | 0 |  |
| GPIO2 | Pull-down | Don't-care |  | 0 |  |
| Debugging Log on UOTXD During Booting |  |  |  |  |  |
| Pin | Default | UOTXD Toggling |  | UOTXD Silent |  |
| MTDO | Pull-up | 1 |  | 0 |  |
| Timing of SDIO Slave |  |  |  |  |  |
| Pin | Default | Falling-edge Input Falling-edge Output | Falling-edge Input Rising-edge Output | Rising-edge Input Falling-edge Output | Rising-edge Input Rising-edge Output |
| MTDO | Pull-up | 0 | 0 | 1 | 1 |
| GPIO5 | Pull-up | 0 | 1 | 0 | 1 |

## Note:

Firmware can configure register bits to change the settings of "Voltage of Internal LDO (VDD_SDIO)" and "Timing of SDIO Slave" after booting.

## 3. Functional Description

This chapter describes the modules and functions integrated in ESP-WROOM-32.

### 3.1 CPU and Internal Memory

ESP32 contains two low-power Xtensa ${ }^{\circledR}$ 32-bit LX6 microprocessors. The internal memory includes:

- 448 KBytes ROM for booting and core functions.
- 520 KBytes on-chip SRAM for data and instruction.
- 8 KBytes SRAM in RTC, which is called RTC SLOW Memory and can be accessed by the co-processor during the Deep-sleep mode.
- 8 KBytes SRAM in RTC, which is called RTC FAST Memory and can be used for data storage; it is accessed by the main CPU during RTC Boot from the Deep-sleep mode.
- 1 Kbit of EFUSE, of which 256 bits are used for the system (MAC address and chip configuration) and the remaining 768 bits are reserved for customer applications, including Flash-Encryption and Chip-ID.


### 3.2 External Flash and SRAM

ESP32 supports $4 \times 16$ MBytes of external QSPI flash and SRAM with hardware encryption based on AES to protect developer's programs and data.

ESP32 accesses the external QSPI flash and SRAM through high-speed caches.

- Up to 16 MBytes of external flash are memory-mapped onto the CPU code space, supporting 8, 16 and 32-bit access. Code execution is supported.
- Up to 8 MBytes of external SRAM are memory-mapped onto the CPU data space, supporting 8, 16 and 32 -bit access. Data-read is supported on the flash and SRAM. Data-write is supported on the SRAM.


### 3.3 Crystal Oscillators

The frequencies of the main crystal oscillator supported include $40 \mathrm{MHz}, 26 \mathrm{MHz}$ and 24 MHz . The accuracy of crystal oscillators applied should be $\pm 10 \mathrm{PPM}$, and the operating temperature ranges from $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$.

When using the downloading tools, remember to select the right crystal oscillator type. In circuit design, capacitors C1 and C2 that connect to the earth are added to the input and output terminals of the crystal oscillator, respectively. The values of the two capacitors can be flexible, ranging from 6 pF to 22 pF . However, the specific capacitive values of C1 and C2 depend on further tests and adjustments of the overall performance of the whole circuit. Normally, the capacitive values of C 1 and C 2 are within 10 pF when the crystal oscillator frequency is 26 MHz , or $10 \mathrm{pF}<\mathrm{C} 1$ and $\mathrm{C} 2<22 \mathrm{pF}$ when the crystal oscillator frequency is 40 MHz .

The frequency of the RTC crystal oscillator is typically 32 kHz or 32.768 kHz . The accuracy can be out of the range of $\pm 20$ PPM, when the internal calibration is applied to correct the frequency offset. When the chip operates in low-power modes, the application chooses the external low-speed ( 32 kHz ) crystal clock, rather than the internal RC oscillators, to achieve the accurate wakeup time.

### 3.4 Power Consumption

With the advanced power management technology, ESP32 can switch between different power modes as follows:

- Power mode
- Active mode: chip radio is powered on. The chip can receive, transmit, or listen.
- Modem-sleep mode: the CPU is operational and the clock is configurable. Wi-Fi / Bluetooth baseband and radio are disabled.
- Light-sleep mode: the CPU is paused. The RTC and ULP-coprocessor are running. Any wake-up events (MAC, host, RTC timer, or external interrupts) will wake up the chip.
- Deep-sleep mode: Only RTC is powered on. Wi-Fi and Bluetooth connection data are stored in RTC memory. The ULP-coprocessor can work.
- Hibernation mode: The internal 8MHz oscillator and ULP-coprocessor are disabled. The RTC recovery memory is powered down. Only one RTC timer on the slow clock and some RTC GPIOs are active. The RTC timer or the RTC GPIOs can wake up the chip from the Hibernation mode.
- Sleep Pattern
- Association sleep pattern: The power mode switches between the active mode and Modem-sleep/Lightsleep mode during this sleep pattern. The CPU, Wi-Fi, Bluetooth, and radio wake up at pre-determined intervals to keep Wi-Fi / BT connections on.
- ULP sensor-monitored pattern: The main CPU is in the Deep-sleep mode. The ULP co-processor does sensor measurements and wakes up the main system, based on the measured data from sensors.

The power consumption varies with different power modes/sleep patterns, and work status, of functional modules (see Table 5).

Table 5: Power Consumption by Power Modes

| Power mode | Comment | Power consumption |
| :---: | :---: | :---: |
| Active mode (RF working) | Wi-Fi Tx packet $13 \mathrm{dBm} \sim 21 \mathrm{dBm}$ | 160 ~ 260 mA |
|  | Wi-Fi / BT Tx packet 0 dBm | 120 mA |
|  | Wi-Fi / BT Rx and listening | $80 \sim 90 \mathrm{~mA}$ |
|  | Association sleep pattern (by Lightsleep) | 0.9 mA@DTIM3, $1.2 \mathrm{mA@DTIM1}$ |
| Modem-sleep mode | The CPU is powered on. | Max speed: 20 mA |
|  |  | Normal: $5 \sim 10 \mathrm{~mA}$ |
|  |  | Slow speed: 3 mA |
| Light-sleep mode | - | 0.8 mA |
| Deep-sleep mode | The ULP-coprocessor is powered on. | 0.15 mA |
|  | ULP sensor-monitored pattern | $25 \mu \mathrm{~A} @ 1 \%$ duty |
|  | RTC timer + RTC memories | $20 \mu \mathrm{~A}$ |
| Hibernation mode | RTC timer only | $5 \mu \mathrm{~A}$ |

### 3.5 Peripherals and Sensors

### 3.5.1 Peripherals and Sensors Description

Table 6: Peripherals and Sensors Description

| Interface | Signal | Pin | Function |
| :---: | :---: | :---: | :---: |
| ADC | ADC1_CH0 | SENSOR_VP | Two 12-bit SAR ADCs |
|  | ADC1_CH3 | SENSOR_VN |  |
|  | ADC1_CH4 | 1032 |  |
|  | ADC1_CH5 | 1 O 33 |  |
|  | ADC1_CH6 | IO34 |  |
|  | ADC1_CH7 | 1035 |  |
|  | ADC2_CH0 | 104 |  |
|  | ADC2_CH1 | 100 |  |
|  | ADC2_CH2 | 1 O 2 |  |
|  | ADC2_CH3 | 1015 |  |
|  | ADC2_CH4 | 1013 |  |
|  | ADC2_CH5 | 1012 |  |
|  | ADC2_CH6 | 1 O 14 |  |
|  | ADC2_CH7 | 1 O 27 |  |
|  | ADC2_CH8 | 1 O 25 |  |
|  | ADC2_CH9 | 1 O 26 |  |
| Ultra Low Noise | SENSOR_VP | 1036 | Provides about 60dB gain by using larger capacitors on PCB |
| Analog Pre-Amplifier | SENSOR_VN | IO39 |  |
| DAC | DAC_1 | IO25 | Two 8-bit DACs |
|  | DAC_2 | 1 O 26 |  |
| Touch Sensor | TOUCH0 | IO4 | Capacitive touch sensors |
|  | TOUCH1 | 100 |  |
|  | TOUCH2 | 1 O 2 |  |
|  | TOUCH3 | 1015 |  |
|  | TOUCH4 | 1013 |  |
|  | TOUCH5 | 1012 |  |
|  | TOUCH6 | 1 O 14 |  |
|  | TOUCH7 | 1 O 27 |  |
|  | TOUCH8 | 1 O 33 |  |
|  | TOUCH9 | 1032 |  |
| SD / SDIO / MMC Host Controller | HS2_CLK | MTMS | Supports SD memory card V3.01 standard |
|  | HS2_CMD | MTDO |  |
|  | HS2_DATA0 | IO2 |  |
|  | HS2_DATA1 | IO4 |  |
|  | HS2_DATA2 | MTDI |  |
|  | HS2_DATA3 | MTCK |  |


| Interface | Signal | Pin | Function |
| :---: | :---: | :---: | :---: |
| Motor PWM | PWMO_OUTO~2 | Any GPIO | Three channels of 16-bit timers generate PWM waveforms; each has a pair of output signals. Three fault detection signals. Three even capture signals. Three sync signals. |
|  | PWM1_OUT_INO~2 |  |  |
|  | PWMO_FLT_INO~2 |  |  |
|  | PWM1_FLT_INO~2 |  |  |
|  | PWMO_CAP_INO~2 |  |  |
|  | PWM1_CAP_INO~2 |  |  |
|  | PWMO_SYNC_INO~2 |  |  |
|  | PWM1_SYNC_INO~2 |  |  |
| LED PWM | ledc_hs_sig_out0~7 | Any GPIO | 16 independent channels @80MHz clock/RTC CLK. Duty accuracy: 16bits. |
|  | ledc_Is_sig_out0~7 |  |  |
| UART | UORXD_in | Any GPIO | Two UART devices with hardware flow-control and DMA |
|  | U0CTS_in |  |  |
|  | UODSR_in |  |  |
|  | UOTXD_out |  |  |
|  | UORTS_out |  |  |
|  | UODTR_out |  |  |
|  | U1RXD_in |  |  |
|  | U1CTS_in |  |  |
|  | U1TXD_out |  |  |
|  | U1RTS_out |  |  |
|  | U2RXD_in |  |  |
|  | U2CTS_in |  |  |
|  | U2TXD_out |  |  |
|  | U2RTS_out |  |  |
| 12C | I2CEXTO_SCL_in | Any GPIO | Two I2C devices in slave or master modes |
|  | I2CEXTO_SDA_in |  |  |
|  | 12CEXT1_SCL_in |  |  |
|  | I2CEXT1_SDA_in |  |  |
|  | I2CEXTO_SCL_out |  |  |
|  | I2CEXTO_SDA_out |  |  |
|  | 12CEXT1_SCL_out |  |  |
|  | I2CEXT1_SDA_out |  |  |


| Interface | Signal | Pin | Function |
| :---: | :---: | :---: | :---: |
| 12S | I2SOI_DATA_in0~15 | Any GPIO | Stereo input and output from/to the audio codec, and parallel LCD data output |
|  | I2SOO_BCK_in |  |  |
|  | 12S0O_WS_in |  |  |
|  | 12SOI_BCK_in |  |  |
|  | 12SOI_WS_in |  |  |
|  | I2SOI_H_SYNC |  |  |
|  | I2SOI_V_SYNC |  |  |
|  | I2SOI_H_ENABLE |  |  |
|  | 12S0O_BCK_out |  |  |
|  | 12S0O_WS_out |  |  |
|  | I2SOI_BCK_out |  |  |
|  | I2SOI_WS_out |  |  |
|  | 12S0O_DATA_out0~23 |  |  |
|  | I2S1I_DATA_in0~15 |  |  |
|  | 12S1O_BCK_in |  |  |
|  | 12S1O_WS_in |  |  |
|  | 12S1I_BCK_in |  |  |
|  | 12S11_WS_in |  |  |
|  | I2S1I_H_SYNC |  |  |
|  | I2S11_V_SYNC |  |  |
|  | I2S11_H_ENABLE |  |  |
|  | I2S1O_BCK_out |  |  |
|  | 12S1O_WS_out |  |  |
|  | 12S1I_BCK_out |  |  |
|  | I2S11_WS_out |  |  |
|  | 12S1O_DATA_out0~23 |  |  |
| Remote Controller | RMT_SIG_INO~7 | Any GPIO | Eight channels of IR transmitter and receiver for various waveforms |
|  | RMT_SIG_OUTO~7 |  |  |


| Interface | Signal | Pin | Function |
| :---: | :---: | :---: | :---: |
| Parallel QSPI | SPIHD | SHD/SD2 | Supports Standard SPI, Dual SPI, and Quad SPI that can be connected to the external flash and SRAM |
|  | SPIWP | SWP/SD3 |  |
|  | SPICSO | SCS/CMD |  |
|  | SPICLK | SCK/CLK |  |
|  | SPIQ | SDO/SD0 |  |
|  | SPID | SDI/SD1 |  |
|  | HSPICLK | 1014 |  |
|  | HSPICSO | 1015 |  |
|  | HSPIQ | 1012 |  |
|  | HSPID | 1013 |  |
|  | HSPIHD | 104 |  |
|  | HSPIWP | 102 |  |
|  | VSPICLK | 1018 |  |
|  | VSPICSO | 105 |  |
|  | VSPIQ | 1019 |  |
|  | VSPID | 1 O 23 |  |
|  | VSPIHD | 1 O 21 |  |
|  | VSPIWP | 1 O 22 |  |
| General Purpose SPI | HSPIQ_in/_out | Any GPIO | Standard SPI consists of clock, chip-select, MOSI and MISO. These SPIs can be connected to LCD and other external devices. They support the following features: <br> (a) both master and slave modes; <br> (b) 4 sub-modes of the SPI format transfer that depend on the clock phase (CPHA) and clock polarity (CPOL) control; <br> (c) CLK frequencies by a divider; <br> (d) up to 64byte FIFO and DMA. |
|  | HSPID_in/_out |  |  |
|  | HSPICLK_in/_out |  |  |
|  | HSPI_CSO_in/_out |  |  |
|  | HSPI_CS1_out |  |  |
|  | HSPI_CS2_out |  |  |
|  | VSPIQ_in/_out |  |  |
|  | VSPID_in/_out |  |  |
|  | VSPICLK_in/_out |  |  |
|  | VSPI_CSO_in/_out |  |  |
|  | VSPI_CS1_out |  |  |
|  | VSPI_CS2_out |  |  |
| JTAG | MTDI | 1012 | JTAG for software debugging |
|  | MTCK | 1013 |  |
|  | MTMS | 1014 |  |
|  | MTDO | 1015 |  |


| Interface | Signal | Pin | Function |
| :---: | :---: | :---: | :---: |
| SDIO Slave | SD_CLK | 106 | SDIO interface that conforms to the industry standard SDIO 2.0 card specification. |
|  | SD_CMD | 1011 |  |
|  | SD_DATA0 | 107 |  |
|  | SD_DATA1 | 108 |  |
|  | SD_DATA2 | 109 |  |
|  | SD_DATA3 | 1010 |  |
| EMAC | EMAC_TX_CLK | 100 | Ethernet MAC with MII/RMII interface |
|  | EMAC_RX_CLK | 105 |  |
|  | EMAC_TX_EN | 1 O 21 |  |
|  | EMAC_TXDO | 1019 |  |
|  | EMAC_TXD1 | 1 O 22 |  |
|  | EMAC_TXD2 | 1014 |  |
|  | EMAC_TXD3 | 1 O 12 |  |
|  | EMAC_RX_ER | 1013 |  |
|  | EMAC_RX_DV | 1027 |  |
|  | EMAC_RXDO | 1 O 25 |  |
|  | EMAC_RXD1 | 1 O 26 |  |
|  | EMAC_RXD2 | TXD |  |
|  | EMAC_RXD3 | 1015 |  |
|  | EMAC_CLK_OUT | 1016 |  |
|  | EMAC_CLK_OUT_180 | 1017 |  |
|  | EMAC_TX_ER | 104 |  |
|  | EMAC_MDC_out | Any GPIO |  |
|  | EMAC_MDI_in | Any GPIO |  |
|  | EMAC_MDO_out | Any GPIO |  |
|  | EMAC_CRS_out | Any GPIO |  |
|  | EMAC_COL_out | Any GPIO |  |

## Note:

Functions of Motor PWM, LED PWM, UART, I2C, I2S, general purpose SPI and Remote Controller can be configured to any GPIO.

### 3.5.2 Peripheral Schematics



Figure 2: ESP-WROOM-32 Peripheral Schematics

## Note:

The MTDI should be kept at low electric level.

## 4. Electrical Characteristics

## Note:

The specifications in this chapter have been tested under the following general condition: $\mathrm{V}_{B A T}=3.3 \mathrm{~V}, \mathrm{~T}_{A}=27^{\circ} \mathrm{C}$, unless otherwise specified.

### 4.1 Absolute Maximum Ratings

Table 7: Absolute Maximum Ratings

| Rating | Condition | Value | Unit |
| :--- | :--- | :--- | :--- |
| Storage temperatue | - | $-40 \sim 85$ | ${ }^{\circ} \mathrm{C}$ |
| Maximum soldering temperature | - | 260 | ${ }^{\circ} \mathrm{C}$ |
| Supply voltage | IPC/JEDEC J-STD-020 | $+2.2 \sim+3.6$ | V |

### 4.2 Recommended Operating Conditions

Table 8: Recommended Operating Conditions

| Operating condition | Symbol | Min | Typ | Max | Unit |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Operating temperature | - | -40 | 20 | 85 | ${ }^{\circ} \mathrm{C}$ |
| Supply voltage | VDD | 2.2 | 3.3 | 3.6 | V |

### 4.3 Digital Terminal Characteristics

Table 9: Digital Terminal Characteristics

| Terminals | Symbol | Min | Typ | Max | Unit |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Input logic level low | $\mathrm{V}_{I L}$ | -0.3 | - | 0.25 VDD | V |
| Input logic level high | $\mathrm{V}_{I H}$ | 0.75 VDD | - | $\mathrm{VDD}+0.3$ | V |
| Output logic level low | $\mathrm{V}_{O L}$ | N | - | 0.1 VDD | V |
| Output logic level high | $\mathrm{V}_{O H}$ | 0.8 VDD | - | N | V |

### 4.4 Wi-Fi Radio

Table 10: Wi-Fi Radio Characteristics

| Description | Min | Typical | Max | Unit |
| :---: | :---: | :---: | :---: | :---: |
| General Characteristics |  |  |  |  |
| Input frequency | 2412 | - | 2484 | MHz |
| Input impedance | - | 50 | - | $\Omega$ |
| Input reflection | - | - | -10 | dB |
| Output power of PA | 15.5 | 16.5 | 21.5 | dBm |
| Sensitivity |  |  |  |  |
| DSSS, 1 Mbps | - | -98 | - | dBm |
| CCK, 11 Mbps | - | -90 | - | dBm |
| OFDM, 6 Mbps | - | -93 | - | dBm |
| OFDM, 54 Mbps | - | -75 | - | dBm |
| HT20, MCS0 | - | -93 | - | dBm |
| HT20, MCS7 | - | -73 | - | dBm |
| HT40, MCS0 | - | -90 | - | dBm |
| HT40, MCS7 | - | -70 | - | dBm |
| MCS32 | - | -91 | - | dBm |
| Adjacent Channel Rejection |  |  |  |  |
| OFDM, 6 Mbps | - | 37 | - | dB |
| OFDM, 54 Mbps | - | 21 | - | dB |
| HT20, MCS0 | - | 37 | - | dB |
| HT20, MCS7 | - | 20 | - | dB |

### 4.5 Bluetooth LE Radio

### 4.5.1 Receiver

Table 11: Receiver Characteristics - BLE

| Parameter | Conditions | Min | Typ | Max | Unit |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Sensitivity @0.1\% BER | - | - | -98 | - | dBm |
| Maximum received signal @0.1\% BER | - | 0 | - | - | dBm |
| Co-channel C/I | - | - | +10 | - | dB |
| Adjacent channel selectivity C/I | $\mathrm{F}=\mathrm{FO}+1 \mathrm{MHz}$ | - | -5 | - | dB |
|  | $\mathrm{F}=\mathrm{FO}-1 \mathrm{MHz}$ | - | -5 | - | dB |
|  | $\mathrm{F}=\mathrm{FO}+2 \mathrm{MHz}$ | - | -25 | - | dB |
|  | $\mathrm{F}=\mathrm{FO}-2 \mathrm{MHz}$ | - | -35 | - | dB |
|  | $\mathrm{F}=\mathrm{FO}+3 \mathrm{MHz}$ | - | -25 | - | dB |
|  | $\mathrm{F}=\mathrm{FO}-3 \mathrm{MHz}$ | - | -45 | - | dB |
| Out-of-band blocking performance | $30 \mathrm{MHz}-2000 \mathrm{MHz}$ | -10 | - | - | dBm |
|  | $2000 \mathrm{MHz}-2400 \mathrm{MHz}$ | -27 | - | - | dBm |
|  | $2500 \mathrm{MHz}-3000 \mathrm{MHz}$ | -27 | - | - | dBm |
|  | $3000 \mathrm{MHz}-12.5 \mathrm{GHz}$ | -10 | - | - | dBm |

### 4.5.2 Transmit

Table 12: Transmit Characteristics - BLE

| Parameter | Conditions | Min | Typ | Max | Unit |
| :--- | :--- | :--- | :--- | :--- | :--- |
| RF transmit power | - | - | +7.5 | +10 | dBm |
| RF power control range | - | - | 25 | - | dB |
| Adjacent channel transmit power | $\mathrm{F}=\mathrm{FO}+1 \mathrm{MHz}$ | - | -14.6 | - | dBm |
|  | $\mathrm{F}=\mathrm{FO}-1 \mathrm{MHz}$ | - | -12.7 | - | dBm |
|  | $\mathrm{F}=\mathrm{FO}+2 \mathrm{MHz}$ | $-\mathrm{FHz}^{2}+3 \mathrm{MHz}$ | -44.3 | - | dBm |
|  | $\mathrm{F}=\mathrm{FO}-3 \mathrm{MHz}$ | - | -38.7 | - | dBm |
|  | $\mathrm{F}=\mathrm{FO}+>3 \mathrm{MHz}$ | - | -49.2 | - | dBm |
|  | $\mathrm{F}=\mathrm{FO}->3 \mathrm{MHz}$ | - | -44.7 | - | dBm |
| $\Delta \mathrm{f} 1_{\text {avg }}$ | - | - | -50 | - | dBm |
| $\Delta \mathrm{f} 2_{\max }$ | - | -50 | - | dBm |  |
| $\Delta \mathrm{f} 2_{\text {avg }} / \Delta \mathrm{f} 1_{\text {avg }}$ | - | - | 265 | kHz |  |
| ICFT | - | - | -0.92 | - | - |
| Drift rate | - | - | -10 | - | kHz |
| Drift | - | - | 0.7 | - | $\mathrm{kHz} / 50 \mu \mathrm{~s}$ |

### 4.6 Reflow Profile

Table 13: Reflow Profile

| Item | Value |
| :---: | :---: |
| $\mathrm{T}_{s}$ max to TL (Ramp-up Rate) | $3^{\circ} \mathrm{C} /$ second max |
| Preheat |  |
| Temperature Min. ( $T_{s}$ Min.) | $150^{\circ} \mathrm{C}$ |
| Temperature Typ. ( $\mathrm{T}_{s}$ Typ.) | $175^{\circ} \mathrm{C}$ |
| Temperature Min. ( $T_{s}$ Max.) | $200^{\circ} \mathrm{C}$ |
| Time ( $\mathrm{T}_{s}$ ) | $60 \sim 180$ seconds |
| Ramp-up rate ( $\mathrm{T}_{L}$ to $\mathrm{T}_{P}$ ) | $3^{\circ} \mathrm{C} /$ second max |
| Time maintained above: -Temperature $\left(\mathrm{T}_{L}\right) /$ Time $\left(\mathrm{T}_{L}\right)$ | $217^{\circ} \mathrm{C} / 60 \sim 150$ seconds |
| Peak temperature ( $\mathrm{T}_{P}$ ) | $260^{\circ} \mathrm{C}$ max, for 10 seconds |
| Target peak temperature ( $\mathrm{T}_{P}$ Target) | $260^{\circ} \mathrm{C}+0 /-5^{\circ} \mathrm{C}$ |
| Time within $5^{\circ} \mathrm{C}$ of actual peak ( $\mathrm{t}_{P}$ ) | $20 \sim 40$ seconds |
| $\mathrm{T}_{S}$ max to $\mathrm{T}_{L}$ (Ramp-down Rate) | $6^{\circ} \mathrm{C} /$ second $\max$ |
| Tune $25^{\circ} \mathrm{C}$ to Peak Temperature (t) | 8 minutes max |

## Note:

The 32 kHz crystal is internally connected to ESP32's GPIO32 and GPIO33. To use ADC, Touch or GPIO functions of IO32 and IO33, please remove the 32 kHz crystal and its capacitors - C13 and C17, and solder the 0ohm resistors R5 and R6.

## 5. Schematics



Figure 3: ESP-WROOM-32 Schematics

## Note:

The capacitance of C1 and C2 varies with the selection of the crystal.

