## ebm-papst Mulfingen GmbH & Co. KG

Bachmühle 2 D-74673 Mulfingen Phone +49 (0) 7938 81-0 Fax +49 (0) 7938 81-110 info1@de.ebmpapst.com www.ebmpapst.com

## CONTENTS

## 1. SAFETY REGULATIONS AND NOTES

1.1 Levels of hazard warnings	1
1.2 Staff qualification	1
1.3 Basic safety rules	1
1.4 Electrical voltage	1
1.5 Safety and protective functions	2
1.6 Electromagnetic radiation	2
1.7 Mechanical movement	2
1.8 Emission	2
1.9 Hot surface	2
1.10 Transport	2
1.11 Storage	2

## 2. PROPER USE

## TEOUNIOAL DAT

3. TECHNICAL DATA	4
3.1 Product drawing	4
3.2 Nominal data	5
3.3 Technical features	5
3.4 Mounting data	5
3.5 Transport and storage conditions	5
3.6 Electromagnetic compatibility	5
4. CONNECTION AND START-UP	6
4.1 Connecting the mechanical system	6
4.2 Connecting the electrical system	6
4.3 Connection via plug	7
4.4 Connection screen	8
4.5 Checking the connections	9
4.6 Switch on device	9
4.7 Switching off the device	9
5. INTEGRATED PROTECTIVE FUNCTIONS	9
6. MAINTENANCE, MALFUNCTIONS, POSSIBLE CAUSES AND REMEDIES	9

6.1 Cleaning

6.3 Disposal

6.2 Safety test

## **1. SAFETY REGULATIONS AND NOTES**

Please read these operating instructions carefully before starting to work with the device. Observe the following warnings to prevent malfunctions or physical damage to both property and people.

These operating instructions are to be regarded as part of this device. If the device is sold or transferred, the operating instructions must accompany it.

These operating instructions may be duplicated and forwarded for information about potential dangers and their prevention.

## 1.1 Levels of hazard warnings

These operating instructions use the following hazard levels to indicate potentially hazardous situations and important safety regulations:



1

3

10

10

10

## DANGER

Indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury. Compliance with the measures is mandatory.

## WARNING

Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury. Exercise extreme caution while working.

## CAUTION

Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury or damage of property.

### NOTE

A potentially harmful situation can occur and, if not avoided, can lead to property damage.

## 1.2 Staff qualification

The device may only be transported, unpacked, installed, operated, maintained and otherwise used by qualified, trained and authorised technical staff.

Only authorised specialists are permitted to install the device, to carry out a test run and to perform work on the electrical installation.

## 1.3 Basic safety rules

Any safety hazards stemming from the device must be re-evaluated once it is installed in the end device.

The local industrial safety regulations must always be observed when working on the device.

Keep the workplace clean and tidy. Untidiness in the working area increases the risk of injury.

Observe the following when working on the unit:

⇒ Do not make any modifications, additions or conversions to the device without the approval of ebm-papst.

## 1.4 Electrical voltage

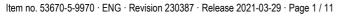
DANGER

- ⇒ Check the electrical equipment of the device at regular intervals, refer to chapter 6.2 Safety test.
- Replace loose connections and defective cables immediately. ⇒



Electrical load on the device Risk of electric shock

→ Stand on a rubber mat if you are working on an electrically charged device.





## **Operating instructions**



## WARNING

Terminals and connections have voltage even with a unit that is shut off Electric shock

→ Wait five minutes after disconnecting the voltage at all poles before opening the device.

#### CAUTION

## In the event of failure, there is electric voltage at the rotor and impeller

The rotor and impeller are base insulated.

 $\rightarrow$  Do not touch the rotor and impeller once they are installed.

#### CAUTION

If control voltage is applied or a speed setpoint is stored, the motor will restart automatically, e.g. after a mains failure.

#### Risk of injury

- $\rightarrow$  Keep out of the device hazard zone.
- → When working on the device, switch off the mains power and ensure that it cannot be switched back on.
- $\rightarrow$  Wait until the device stops.
- → After working on the device, remove any tools used or other objects from the device.

### 1.5 Safety and protective functions



#### Guard missing and guard not functioning

Without a guard there is a risk of serious injury, for instance when reaching into the device during operation. Loose parts or items of clothing could be drawn in.

- → The device is a built-in component. As the operator, you are responsible for ensuring that the device is secured adequately.# Operate the device only with a fixed protective device and guard grille.
- → Stop the device immediately if a protective device is found to be missing or ineffective.

## 1.6 Electromagnetic radiation

Interference from electromagnetic radiation is possible, e.g. in conjunction with open and closed-loop control devices.

If unacceptable emission intensities occur when the fan is installed, appropriate shielding measures have to be taken by the user.

#### NOTE

# Electrical or electromagnetic interferences after integrating the device in installations on the customer's side.

 $\rightarrow$  Verify that the entire setup is EMC compliant.

## 1.7 Mechanical movement



#### DANGER Rotating device

Body parts that come into contact with the rotor and impeller can be injured.

- $\rightarrow$  Secure the device against accidental contact.
- → Before working on the system/machine, wait until all parts have come to a standstill.

## WARNING

#### **Rotating device**

Long hair, dangling items of clothing, jewellery and similar items can become entangled and be pulled into the device. Risk of injury.

- → Do not wear any loose-fitting or dangling clothing or jewellery while working on rotating parts.
- $\rightarrow$  Protect long hair with a cap.

### 1.8 Emission

### WARNING

Depending on the installation and operating conditions, a sound pressure level greater than 70 dB(A) may arise. Danger of noise-induced hearing loss

- → Take appropriate technical safety measures.
- → Protect operating personnel with appropriate safety equipment, e.g. hearing protection.
- $\rightarrow$  Also observe the requirements of local agencies.

## 1.9 Hot surface



#### CAUTION High temperature at the electronics housing Risk of burns

 $\rightarrow$  Ensure sufficient contact protection.

## 1.10 Transport

NOTE



## Transporting the device

→ Transport the device in its original packaging only.

## 1.11 Storage

- ⇒ Store the device, partially or fully assembled, in the original packaging in a clean, dry and weatherproof place free of vibrations.
- ⇒ Protect the device against environmental effects and dirt until final installation.
- ⇒ We recommend storing the device for no longer than one year in order to guarantee trouble-free operation and longest possible service life.
- ⇒ Even devices explicitly intended for outdoor use are to be stored as described prior to commissioning.
- Maintain the storage temperature, see chapter 3.5 Transport and storage conditions.



## **Operating instructions**

## 2. PROPER USE

The device is exclusively designed as a built-in device for conveying air according to its technical data.

Any other usage above and beyond this does not conform with the intended purpose and constitutes misuse of the device.

Customer equipment must be capable of withstanding the mechanical and thermal stresses that can arise from this product. This applies for the entire service life of the equipment in which this product is installed.

### Proper use also includes:

- Use of the device in stationary systems only.
- Carrying out all maintenance.
- Conveying of air at an ambient air pressure of 800 mbar to 1050 mbar.
- Using the device in accordance with the permitted ambient temperature, see chapter 3.5 Transport and storage conditions and chapter 3.2 Nominal data.
- Operating the device with all protective features in place.
- Minding the operating instructions.

### Improper use

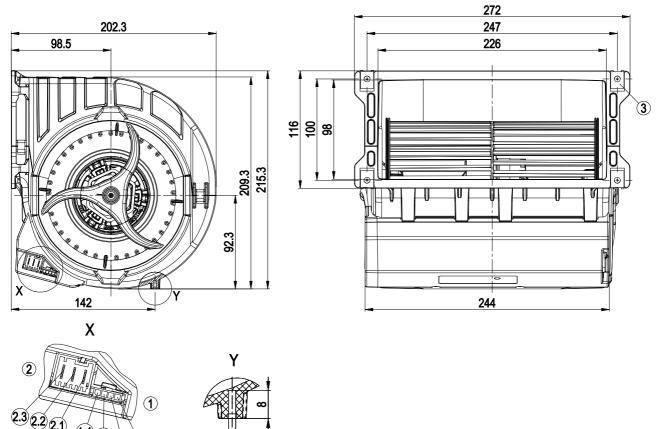
Using the device in the following ways is particularly prohibited and may cause hazards:

- Operating the device with an imbalance, e.g. caused by dirt deposits or icing.
- Resonance mode, operation with heavy vibrations. These also include vibrations that are transmitted from the customer system to the fan.
- Operation in medical equipment with a life-sustaining or lifesaving function.
- Moving solids content in flow medium.
- Painting the device
- Connections (e.g. screws) coming loose during operation.
- · Moving air that contains abrasive particles.
- Moving highly corrosive air, e.g. salt spray mist. Exceptions are devices that are intended for salt spray mist and protected accordingly.
- Moving air that contains dust pollution, e.g. suctioning off saw dust.
- · Operating the device close to flammable materials or components.
- Operating the device in an explosive atmosphere.
- Using the device as a safety component or for taking on safetyrelated functions.
- Operation with completely or partially disassembled or modified protective features.
- In addition, all application options that are not listed under proper use.



## 3. TECHNICAL DATA

## 3.1 Product drawing



All measures have the unit mm.

1	Strip Molex Micro Fit 3.0 043650 0400 (pluggable with 043645 0400)
1.1	10 V
1.2	Tach
1.3	0-10 V lin. / PWM
1.4	GND
2	Connector Lumberg 3642 03 K01 (pluggable with 3626 03 K01)
2.1	PE
2.2	L
2.3	Ν
3	4x sheet metal nut for thread EN ISO 1478-ST4.8 (min. screw length 14.5 mm plus thickness of mounting material)



Item no. 53670-5-9970 · ENG · Revision 230387 · Release 2021-03-29 · Page 4 / 11

Ø2.3

1.2 (1.1)

ebm-papst Mulfingen GmbH & Co. KG · Bachmühle 2 · D-74673 Mulfingen · Phone +49 (0) 7938 81-0 · Fax +49 (0) 7938 81-110 · info1@de.ebmpapst.com · www.ebmpapst.com

## **Operating instructions**

### 3.2 Nominal data

<b>NR</b> (	MOODEE DI
Motor	M3G055-BI
	1
Phase	1~
Nominal voltage / VAC	230
Nominal voltage	200 240
range / VAC	
Frequency / Hz	50/60
Tour a state to definition	
Type of data definition	ml
Speed (rpm) / min <sup>-1</sup>	1060
Power input / W	57
Current draw / A	0.5
Min. ambient	-25
temperature / °C	
Max. ambient	60
temperature / °C	

ml = Max. load  $\cdot$  me = Max. efficiency  $\cdot$  fa = Running at free air cs = Customer specs  $\cdot$  cu = Customer unit

Subject to alterations

### 3.3 Technical features

Size146 mmMotor size55Surface of rotorGalvanisedMaterial of electronicsPP plastichousingPP plasticMaterial of impellerPP plasticHousing materialPP plasticMotor suspensionMotor mounted anti-vibration on both sidesDirection of rotationCounter-clockwise, seen on rotorType of protectionMotor IP00, electronics IP20; Depending on installation and positionInsulation class"F"Humidity (F) / environmental protection class (H)H0 - dry environmentMounting positionAnyCondensation drainage holesOn rotor and stator sidesOperation modeS1Motor current limit - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected motorTouch current acc. IEC 60990 (measuring network Fig. 4, TN system)PlugElectrical connectionPlugMotor protectionThermal overload protector (TOP) wired internally		1
Notor size55Surface of rotorGalvanisedMaterial of electronicsPP plasticHousing materialPP plasticMotor suspensionMotor mounted anti-vibration on both sidesDirection of rotationCounter-clockwise, seen on rotorType of protectionMotor IP00, electronics IP20; Depending on installation and positionInsulation class"F"Humidity (F) / environmental protection class (H)H0 - dry environmentMounting positionAnyCondensation drainage holesOn rotor and stator sidesOperation modeS1Motor bearingBall bearingTechnical features- Output 10 VDC, max. 1.1 mA - Tach output - Motor current limit - Soft start - Control input 0-10 VDC / PWM - Control input 0-10 VDC / PWM <b< th=""><th>Mass</th><th>2.2 kg</th></b<>	Mass	2.2 kg
Surface of rotorGalvanisedMaterial of electronicsPP plastichousingPP plasticMaterial of impellerPP plasticHousing materialPP plasticMotor suspensionMotor mounted anti-vibration on both sidesDirection of rotationCounter-clockwise, seen on rotorType of protectionMotor IP00, electronics IP20; Depending on installation and positionInsulation class"F"Humidity (F) / environmental protection class (H)H0 - dry environmentMounting positionAnyCondensation drainage holesOn rotor and stator sidesCooling bore / aperture Operation modeOn rotor and stator sidesOperation mode soft start- Output 10 VDC, max. 1.1 mA - Tach output - Motor current limit - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected motorTouch current acc. IEC 60990 (measuring network Fig. 4, TN system)Simal PlugBelctrical connectionPlugMotor protectionThermal overload protector (TOP) wired internally	Size	146 mm
Material of electronics housing       PP plastic         Material of impeller       PP plastic         Housing material       PP plastic         Motor suspension       Motor mounted anti-vibration on both sides         Direction of rotation       Counter-clockwise, seen on rotor         Type of protection       Motor IP00, electronics IP20; Depending on installation and position         Insulation class       "F"         Humidity (F) / environmental protection class (H)       H0 - dry environment         Mounting position       Any         Condensation       None, open rotor         drainage holes       On rotor and stator sides         Operation mode       S1         Motor bearing       Ball bearing         Technical features       - Output 10 VDC, max. 1.1 mA - Tach output - Motor current limit         - Soft start       - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected motor         Touch current acc.       <= 3.5 mA         IEC 60990 (measuring network Fig. 4, TN system)       Plug         Motor protection       Thermal overload protector (TOP) wired internally	Motor size	55
housingPP plasticMaterial of impellerPP plasticHousing materialPP plasticMotor suspensionMotor mounted anti-vibration on both sidesDirection of rotationCounter-clockwise, seen on rotorType of protectionMotor IP00, electronics IP20; Depending on installation and positionInsulation class"F"Humidity (F) / environmental protection class (H)H0 - dry environmentMounting positionAnyCondensation drainage holesNone, open rotorColoing bore / apertureOn rotor and stator sidesOperation modeS1Motor bearingBall bearingTechnical features- Output 10 VDC, max. 1.1 mA - Tach output - Motor current limit - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected motorTouch current acc. IEC 60990 (measuring network Fig. 4, TN system)<= 3.5 mAElectrical connectionPlugMotor protectionThermal overload protector (TOP) wired internally	Surface of rotor	Galvanised
Material of impellerPP plasticHousing materialPP plasticMotor suspensionMotor mounted anti-vibration on both sidesDirection of rotationCounter-clockwise, seen on rotorType of protectionMotor IP00, electronics IP20; Depending on installation and positionInsulation class"F"Humidity (F) / environmental protection class (H)H0 - dry environmentMounting positionAnyCondensation drainage holesNone, open rotorCooling bore / aperture Operation modeOn rotor and stator sidesOperation mode S1S1Motor bearing - Control input 0-10 VDC, max. 1.1 mA - Tach output - Motor current limit - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected motorTouch current acc. IEC 60990 (measuring network Fig. 4, TN system)<= 3.5 mAElectrical connectionPlugMotor protectionThermal overload protector (TOP) wired internally	Material of electronics	PP plastic
Housing materialPP plasticMotor suspensionMotor mounted anti-vibration on both sidesDirection of rotationCounter-clockwise, seen on rotorType of protectionMotor IP00, electronics IP20; Depending on installation and positionInsulation class"F"Humidity (F) / environmental protection class (H)H0 - dry environmentMounting positionAnyCondensation drainage holesNone, open rotorCooling bore / aperture Operation modeOn rotor and stator sidesOperation mode S1S1Motor bearing - Control input 0-10 VDC, max. 1.1 mA - Tach output - Motor current limit - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected motorTouch current acc. IEC 60990 (measuring network Fig. 4, TN system)PlugElectrical connectionPlugMotor protectionThermal overload protector (TOP) wired internally	housing	
Motor suspensionMotor mounted anti-vibration on both sidesDirection of rotationCounter-clockwise, seen on rotorType of protectionMotor IP00, electronics IP20; Depending on installation and positionInsulation class"F"Humidity (F) / environmental protection class (H)H0 - dry environmentMounting positionAnyCondensation drainage holesOn rotor and stator sidesOperation modeS1Motor bearingBall bearingTechnical features- Output 10 VDC, max. 1.1 mA - Tach output- Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected motorTouch current acc. IEC 60990 (measuring network Fig. 4, TN system)Electrical connectionPlugMotor protectionPlug	Material of impeller	PP plastic
Direction of rotationCounter-clockwise, seen on rotorType of protectionMotor IP00, electronics IP20; Depending on installation and positionInsulation class"F"Humidity (F) / environmental protection class (H)H0 - dry environmentMounting positionAnyCondensation drainage holesNone, open rotorCooling bore / aperture Operation modeOn rotor and stator sidesOperation modeS1Motor bearingBall bearingTechnical features- Output 10 VDC, max. 1.1 mA - Tach output- Soft start - Control input 0-10 VDC / PWM - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected motorTouch current acc. IEC 60990 (measuring network Fig. 4, TN system)<= 3.5 mAElectrical connectionPlug Thermal overload protector (TOP) wired internally	Housing material	PP plastic
Type of protection       Motor IP00, electronics IP20; Depending on installation and position         Insulation class       "F"         Humidity (F) / environmental protection class (H)       H0 - dry environment         Mounting position       Any         Condensation drainage holes       On rotor and stator sides         Cooling bore / aperture       On rotor and stator sides         Operation mode       S1         Motor bearing       Ball bearing         Technical features       - Output 10 VDC, max. 1.1 mA         - Tach output       - Motor current limit         - Soft start       - Control input 0-10 VDC / PWM         - Control input 0-10 VDC / PWM       - Control interface with SELV potential safely disconnected from the mains         - Over-temperature protected motor       <= 3.5 mA         Touch current acc.       <= 3.5 mA         IEC 60990 (measuring network Fig. 4, TN system)       Plug         Belectrical connection       Plug         Motor protection       Thermal overload protector (TOP) wired internally	Motor suspension	Motor mounted anti-vibration on both sides
on installation and position         Insulation class       "F"         Humidity (F) /       H0 - dry environment         environmental       protection class (H)         Mounting position       Any         Condensation       None, open rotor         drainage holes       On rotor and stator sides         Cooling bore / aperture       On rotor and stator sides         Operation mode       S1         Motor bearing       Ball bearing         Technical features       - Output 10 VDC, max. 1.1 mA         - Tach output       - Motor current limit         - Soft start       - Control input 0-10 VDC / PWM         - Control interface with SELV potential safely disconnected from the mains         - Over-temperature protected motor         Touch current acc.       <= 3.5 mA         IEC 60990 (measuring network Fig. 4, TN system)       Plug         Electrical connection       Plug         Motor protection       Thermal overload protector (TOP) wired internally	Direction of rotation	Counter-clockwise, seen on rotor
Humidity (F) / environmental protection class (H)       H0 - dry environment         Mounting position       Any         Condensation drainage holes       None, open rotor         Cooling bore / aperture       On rotor and stator sides         Operation mode       S1         Motor bearing       Ball bearing         Technical features       - Output 10 VDC, max. 1.1 mA - Tach output         - Motor current limit       - Soft start         - Control input 0-10 VDC / PWM       - Control interface with SELV potential safely disconnected from the mains         - Over-temperature protected motor       <= 3.5 mA         Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)       <= 3.5 mA         Electrical connection       Plug         Motor protection       Thermal overload protector (TOP) wired internally	Type of protection	on installation and position
environmental protection class (H) Mounting position Any Condensation None, open rotor drainage holes Cooling bore / aperture On rotor and stator sides Operation mode S1 Motor bearing Ball bearing Technical features - Output 10 VDC, max. 1.1 mA - Tach output - Motor current limit - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected motor Touch current acc. IEC 60990 (measuring network Fig. 4, TN system) Electrical connection Plug Motor protection Thermal overload protector (TOP) wired internally	Insulation class	"F"
protection class (H)         Mounting position       Any         Condensation       None, open rotor         drainage holes       On rotor and stator sides         Cooling bore / aperture       On rotor and stator sides         Operation mode       S1         Motor bearing       Ball bearing         Technical features       - Output 10 VDC, max. 1.1 mA         - Tach output       - Motor current limit         - Soft start       - Control input 0-10 VDC / PWM         - Control interface with SELV potential safely disconnected from the mains       - Over-temperature protected motor         Touch current acc.       <= 3.5 mA         IEC 60990 (measuring network Fig. 4, TN system)       Plug         Blectrical connection       Plug         Motor protection       Thermal overload protector (TOP) wired internally	Humidity (F) /	H0 - dry environment
Mounting position       Any         Condensation       None, open rotor         drainage holes       On rotor and stator sides         Cooling bore / aperture       On rotor and stator sides         Operation mode       S1         Motor bearing       Ball bearing         Technical features       - Output 10 VDC, max. 1.1 mA         - Tach output       - Motor current limit         - Soft start       - Control input 0-10 VDC / PWM         - Control interface with SELV potential safely disconnected from the mains         - Over-temperature protected motor         Touch current acc.         IEC 60990 (measuring network Fig. 4, TN system)         Electrical connection       Plug         Motor protection       Thermal overload protector (TOP) wired internally	environmental	
Condensation drainage holes       None, open rotor         Cooling bore / aperture       On rotor and stator sides         Operation mode       S1         Motor bearing       Ball bearing         Technical features       - Output 10 VDC, max. 1.1 mA         - Tach output       - Motor current limit         - Soft start       - Control input 0-10 VDC / PWM         - Control interface with SELV potential safely disconnected from the mains         - Over-temperature protected motor         Touch current acc.         IEC 60990 (measuring network Fig. 4, TN system)         Electrical connection         Plug         Motor protection	protection class (H)	
drainage holes       On rotor and stator sides         Cooling bore / aperture       On rotor and stator sides         Operation mode       S1         Motor bearing       Ball bearing         Technical features       - Output 10 VDC, max. 1.1 mA         - Tach output       - Motor current limit         - Soft start       - Control input 0-10 VDC / PWM         - Control input 0-10 VDC / PWM       - Control interface with SELV potential safely disconnected from the mains         - Over-temperature protected motor       <= 3.5 mA         IEC 60990 (measuring network Fig. 4, TN system)       Plug         Belectrical connection       Plug         Motor protection       Thermal overload protector (TOP) wired internally	Mounting position	Any
Cooling bore / aperture       On rotor and stator sides         Operation mode       S1         Motor bearing       Ball bearing         Technical features       - Output 10 VDC, max. 1.1 mA         - Tach output       - Motor current limit         - Soft start       - Control input 0-10 VDC / PWM         - Control interface with SELV potential safely disconnected from the mains         - Over-temperature protected motor         Touch current acc.         IEC 60990 (measuring network Fig. 4, TN system)         Electrical connection         Plug         Motor protection	Condensation	None, open rotor
Operation mode       S1         Motor bearing       Ball bearing         Technical features       - Output 10 VDC, max. 1.1 mA         - Tach output       - Motor current limit         - Soft start       - Control input 0-10 VDC / PWM         - Control interface with SELV potential safely disconnected from the mains         - Over-temperature protected motor         Touch current acc.         IEC 60990 (measuring network Fig. 4, TN system)         Electrical connection         Plug         Motor protection         Thermal overload protector (TOP) wired internally	drainage holes	
Motor bearing       Ball bearing         Technical features       - Output 10 VDC, max. 1.1 mA         - Tach output       - Motor current limit         - Soft start       - Control input 0-10 VDC / PWM         - Control interface with SELV potential safely disconnected from the mains         - Over-temperature protected motor         Touch current acc.         IEC 60990 (measuring network Fig. 4, TN system)         Electrical connection         Plug         Motor protection	Cooling bore / aperture	
Technical features       - Output 10 VDC, max. 1.1 mA         - Tach output       - Tach output         - Motor current limit       - Soft start         - Control input 0-10 VDC / PWM       - Control interface with SELV potential safely disconnected from the mains         - Over-temperature protected motor          Touch current acc.       <= 3.5 mA         IEC 60990 (measuring network Fig. 4, TN system)       Plug         Blectrical connection       Plug         Motor protection       Thermal overload protector (TOP) wired internally	Operation mode	S1
- Tach output - Motor current limit - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected motor - Over-temperature protected motor - Over-temperature protected motor = 3.5 mA = 3.5 mA = 1000 = 10000 = 1000 = 10000 = 1000 = 1	Motor bearing	
- Motor current limit - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected motor Touch current acc. IEC 60990 (measuring network Fig. 4, TN system) Electrical connection Motor protection Plug Thermal overload protector (TOP) wired internally	Technical features	- Output 10 VDC, max. 1.1 mA
- Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected motor - Over-temperature protected motor = 3.5 mA = 3.5 mA = 1000000000000000000000000000000000000		· · · · · · · · · · · · · · · · · · ·
- Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected motor - Over-temperature protected motor - Over-temperature protected motor = 3.5 mA = 3.5 mA = 1000 (measuring network Fig. 4, TN system) Electrical connection Plug Motor protection Thermal overload protector (TOP) wired internally		
- Control interface with SELV potential safely disconnected from the mains - Over-temperature protected motor - Over-temperature protected motor - Courter acc. IEC 60990 (measuring network Fig. 4, TN system) Electrical connection Motor protection Thermal overload protector (TOP) wired internally		
safely disconnected from the mains       - Over-temperature protected motor       Touch current acc.       IEC 60990 (measuring network Fig. 4, TN system)       Electrical connection       Plug       Motor protection       Thermal overload protector (TOP) wired internally		
- Over-temperature protected motor Touch current acc. IEC 60990 (measuring network Fig. 4, TN system) Electrical connection Plug Motor protection Thermal overload protector (TOP) wired internally		
Touch current acc.       <= 3.5 mA         IEC 60990 (measuring network Fig. 4, TN system)          Electrical connection       Plug         Motor protection       Thermal overload protector (TOP) wired internally		
IEC 60990 (measuring network Fig. 4, TN system)     Plug       Electrical connection     Plug       Motor protection     Thermal overload protector (TOP) wired internally	Tauch aumant and	
network Fig. 4, TN system) Electrical connection Plug Motor protection Thermal overload protector (TOP) wired internally		<= 3.5 mA
system)           Electrical connection         Plug           Motor protection         Thermal overload protector (TOP) wired internally		
Motor protection Thermal overload protector (TOP) wired internally	system)	
internally	Electrical connection	Plug
	Motor protection	Thermal overload protector (TOP) wired
Cable exit Variable		internally
	Cable exit	Variable

Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 60335-1; CE
Approval	CSA C22.2 no. 77 + CAN/CSA- E60730-1; UL 1004-7 + 60730-1



For cyclic speed loads, note that the rotating parts of the device are designed for maximum one million load cycles. If you have specific questions, contact ebm-papst for support.

⇒ Use the device in accordance with its protection type.

### Notes on surface quality

The surfaces of the products conform to the generally applicable industrial standard. The surface quality may vary during the production period. Strength, dimensional stability and dimensional accuracy are not affected by this.

The colour pigments of the paints used react perceptibly to UV light over the course of time. This does not however have any influence on the technical properties of the products. To prevent the formation of patches and fading, the product is to be protected against UV radiation. Changes in colour are not a reason for complaint and are not covered by the warranty.

## 3.4 Mounting data

Any further mounting data required can be taken from the product drawing or Section chapter 4.1 Connecting the mechanical system.

Strength class for	8.8
mounting screws	

For depth of screw, see chapter 3.1 Product drawing

⇒ Secure the mounting screws against accidentally coming loose (e.g. by using self-locking screws).

## 3.5 Transport and storage conditions

Max. permissible ambient motor temp. (transp./ storage)	+ 80 °C
Min. permissible ambient motor temp. (transp./storage)	- 40 °C

## 3.6 Electromagnetic compatibility

EMC interference	Acc. to EN 61000-6-2 (industrial	
immunity	environment)	
EMC harmonics	Acc. to EN 61000-3-2/3	
EMC interference	Acc. to EN 61000-6-3 (household	
emission	environment)	



ebmpapst

## 4. CONNECTION AND START-UP

## 4.1 Connecting the mechanical system



## CAUTION

Cutting and crushing hazard when removing blower from packaging

→ Carefully remove the blower from its packaging by grasping hold of the housing. Never subject to impact.

 $\rightarrow$  Wear safety shoes and cut-resistant safety gloves.



#### NOTE Damage to device from vibration

Bearing damage, reduced service life

- → Forces or impermissibly high vibration levels must not be transmitted to the fan from system components.
- → If the fan is connected to air ducts, it should isolated from vibrations, for example using compensators or similar elements.
- $\rightarrow$  Fasten the fan to the substructure without distorting it.
- ⇒ Check the device for transport damage. Damaged devices must no longer be installed.
- Install the undamaged device according to your application.



#### CAUTION Possibility of damage to the device

Serious damage may result if the device slips during assembly.

- → Keep the device fixed in position at the installation location until all attachment screws have been tightened.
- The fan must not be strained on fastening.

## 4.2 Connecting the electrical system



Electric voltage on the device Electric shock

- $\rightarrow$  Always install a protective earth first.
- $\rightarrow$  Check the protective earth.



#### DANGER Incorrect insulation

Risk of fatal injury from electric shock

- → Use only cables that meet the specified installation requirements for voltage, current, insulation material, load etc.
- → Route cables such that they cannot be touched by any rotating parts.



## DANGER

Electrical load (>50 µC) between mains wire and protective earth connection after switching of the supply when switching multiple devices in parallel. Electric shock, risk of injury

- → Make sure that sufficient protection against accidental contact is provided.
  - Before working on the electrical connection, the connections to the mains supply and PE must be shorted.

## CAUTION

## Electrical voltage

The device is a built-in component and features no electrically isolating switch.

- → Connect the device only to circuits that can be switched off using an all-pole disconnecting switch.
- → When working on the device, you must switch off the system/machine in which the device is installed and secure it from being switched on again.

## NOTE

#### Water penetration into leads or wires

Water enters at the cable end on the customers side and can damage the device.

→ Make sure that the cable end is connected in a dry environment.



Connect the device only to circuits that can be switched off using an all-pole disconnecting switch.

## 4.2.1 Prerequisites

- ⇒ Check that the data on the type plate match the connection data.
- ⇒ Before connecting the device, ensure that the supply voltage matches the operating voltage of the device.
- → Only use cables designed for current according to the type plate. For determining the cross-section, follow the basic principles in accordance with EN 61800-5-1. The protective earth must have a cross-section equal to or greater than the outer conductor crosssection.

We recommend the use of 105°C cables. Ensure that the minimum cable cross-section is at least AWG26/0.13 mm<sup>2</sup>.

## Protective earth contact resistance as per EN 60335

Compliance with the resistance specifications as per EN 60335 for the protective earth connection circuit must be verified in the application. Depending on the installation situation, it may be necessary to connect an additional protective earth conductor by way of the extra protective earth terminal provided on the device.

## 4.2.2 Idle current



Because of the EMC filter integrated for compliance with EMC limits (interference emission and interference immunity), idle currents in the mains cable can be measured even when the motor is at a standstill and the mains voltage is switched on.

- The values are typically in the range < 50 mA
- At the same time, the effective power in this operating state (operational readiness) is typically < 2 W.

## 4.2.3 Residual current operated device



If the use of a residual current device (RCD) is required in your installation, only pulse current-sensitive and/or universal residual current devices (type A or B) are permissible. Residual current devices (RCD) cannot provide personal safety while operating the device, as is also the case with frequency converters. When the device power supply is switched on, charging current pulses from the capacitors in the integrated EMC filter can lead to the instant triggering of residual current devices. We recommend residual current circuit breakers (RCCB) with an activation threshold of 300 mA and delayed tripping (super-resistant, characteristic K).



Item no. 53670-5-9970 · ENG · Revision 230387 · Release 2021-03-29 · Page 6 / 11

## **Operating instructions**

#### 4.2.4 Locked-rotor protection



Due to the locked-rotor protection, the start-up current (LRA) is equal to or less than the nominal current (FLA).

## 4.3 Connection via plug

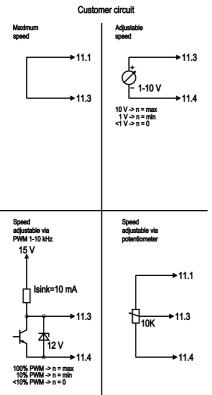
## 4.3.1 Establish supply connections

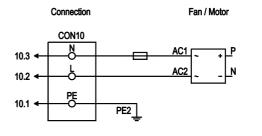
- ⇒ Check the PIN assignment of your connector.
- $\Rightarrow$  Connect the panel connector and mating connector.
- $\Rightarrow$  Ensure that the connector is locked in correctly.

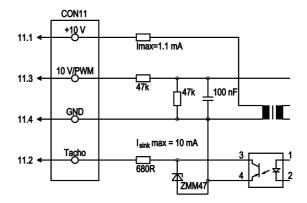


GREEN

## 4.4 Connection screen







No.	Conn.	Designation	Colour	Function / assignment	
CON10	10.1	PE	green/	Protective earth	
			yellow		
CON10	10.2	L	black	Power supply 230 VAC, 50-60 Hz, see type plate for voltage range	
CON10	10.3	N	blue	Neutral conductor	
CON11	11.1	10 V/max. 1.1	red	Voltage output 10 V, 1.1 mA, electrically isolated, not short-circuit-proof	
		mA			
CON11	11.2	Tach	white	Tach output: Open collector, 1 pulse per revolution, electrically isolated, Isink max = 10 mA	
CON11	11.3	0-10 V PWM	yellow	Control input 0-10 V or PWM, electrically isolated	
CON11	11.4	GND	blue	GND connection for control interface	



GREEN

### 4.5 Checking the connections

- ⇒ Make sure that the power is off (all phases).
- ⇒ Secure it from being switched on again.
- ⇒ Check that the mating connector is correctly locked into the panel connector.
- ⇒ Check that the mating connector is correctly crimped to the connection line.

### 4.6 Switch on device

The device is not to be switched on until it has been installed properly and in accordance with its intended use, including the required protective devices and professional electrical connection. This also applies to devices which have already been equipped with plugs and terminals or similar connectors by the customer.



#### WARNING Hot motor housing

Fire hazard

- → Ensure that no combustible or flammable materials are located close to the blower.
- Inspect the device for visible external damage and the proper function of the protective features before switching it on.
- ⇒ Check the air flow paths of the fan for foreign objects and remove any that are found.
- ⇒ Apply the nominal voltage to the voltage supply.
- ⇒ Start the device by changing the input signal.



## Damage to device by vibrations

Bearing damage, reduced service life

- $\rightarrow$  The fan must operate free of vibrations throughout its speed control range.
- → Strong vibrations can result from improper handling, imbalance resulting from damage during transport, or component-induced or structural resonances.
- → When putting the fan into service, determine the speed ranges with excessive vibration levels and also any resonance frequencies that may be present.
- → When regulating the speed, pass through resonance ranges as quickly as possible or find another remedy.
- $\rightarrow$  Operation at excessive vibration levels can lead to premature failure.

## 4.7 Switching off the device

Switching off the device during operation:

- ⇒ Switch off the device via the control input.
- ⇒ Do not switch the motor (e.g. in cyclic operation) on and off via power supply.

Switching off the device for maintenance work:

- ⇒ Switch off the device via the control input.
- ⇒ Do not switch the motor (e.g. in cyclic operation) on and off via power supply.
- ⇒ Disconnect the device from the supply voltage.
- ⇒ When disconnecting, be sure to disconnect the earth wire connection last.

## **5. INTEGRATED PROTECTIVE FUNCTIONS**

The integrated protective functions cause the motor to switch off automatically in case of faults described in the table.

Malfunctions	Description / Function of safety feature
Rotor position detection error	An automatic restart occurs.
Locked rotor	⇒ After the blockage is removed, the motor restarts automatically.
Motor overload	After cooling the device restarts automatically.

## 6. MAINTENANCE, MALFUNCTIONS, POSSIBLE CAUSES AND REMEDIES

Do not perform any repairs on your device. Return the device to ebmpapst for repair or replacement.



## WARNING

Terminals and connections have voltage even with a unit that is shut off Electric shock

 $\rightarrow$  Wait five minutes after disconnecting the voltage at all poles before opening the device.

#### CAUTION

If control voltage is applied or a speed setpoint is stored, the motor will restart automatically, e.g. after a mains failure.

Risk of injury

- $\rightarrow$  Keep out of the device hazard zone.
- → When working on the device, switch off the mains power and ensure that it cannot be switched back on.
- $\rightarrow$  Wait until the device stops.
- → After working on the device, remove any tools used or other objects from the device.



If the device remains out of use for some time, e.g. when in storage, we recommend switching the device on for at least two hours to allow any condensate to evaporate and to move the bearings.

Malfunction/error	Possible cause	Possible remedy
Impeller running roughly	Imbalance in rotating parts	Clean the device; if imbalance is still evident after cleaning,
		replace the device. If you have
		attached any weight clips during cleaning,
		make sure to remove them afterwards.
Motor does not turn	Mechanical blockage	Switch off, de- energise, and remove mechanical
	Mains supply voltage faulty	blockage. Check mains supply voltage, restore power supply, apply control signal.



ebmpapst

Item no. 53670-5-9970 · ENG · Revision 230387 · Release 2021-03-29 · Page 9 / 11

ranslation of the original operating instructions

## **Operating instructions**

	Faulty connection	De-energise, correct connection, see connection diagram.
Overtemperature of electronics/motor	Insufficient cooling	Improve cooling. Let the device cool down. To reset the error message, switch off the mains supply voltage for a min. of 25 s and switch it on again.
	Thermal overload protector responded	Allow motor to cool off, locate and rectify cause of error, if necessary cancel restart lock-out
	Ambient temperature too high	Reduce the ambient temperature. Reset by reducing control input to 0.
	Unacceptable operating point	Correct the operating point. Let the device cool down.

A

If you have any other problems, contact ebm-papst.

## 6.1 Cleaning

DANGER

To ensure a long service life, the fans have to be regularly checked for proper operation and degree of soiling. The frequency of the checks is to be adapted to the occurrence of soiling.



Risk of injury from rotating fan.

- → Only clean when not in motion. Do not disconnect the fan from the power supply, just switch it off via the control input. This will prevent start-up of the fan.
- ⇒ Dirt deposits on the motor housing could lead to overheating of the motor.
- ⇒ Dirt on the impeller can cause vibration which would shorten the service life of the fan.
- ⇒ Severe vibration could destroy the fan.
- ⇒ In such cases immediately switch off and clean the fan.
- ⇒ The preferred method of cleaning is dry cleaning, e.g. using compressed air.
- ⇒ Use is never to be made of corrosive cleaning agents!
- ⇒ Completely remove any cleaning agents used.
- Immediately switch off and replace the device if severe corrosion is apparent at load-bearing or rotating parts.
- ⇒ Repairs to load-bearing or rotating parts are not permissible!
- Operate the fan for 2 hours at maximum speed to permit the evaporation of any water which may have ingressed.
- ⇒ If cleaning does not eliminate vibration, the fan may have to be rebalanced. In such cases please contact ebm-papst.
- ⇒ The fan is provided with maintenance-free ball bearings. The lifetime lubrication of the ball bearings is designed for a service life of 40,000 hours.

- ⇒ Please contact ebm-papst if bearing replacement is required after this period.
- ⇒ Adapt the maintenance intervals to the dust pollution occurring.

## 6.2 Safety test

## NOTE

#### High-voltage test

The integrated EMC filter contains Y capacitors. Therefore, the trigger current is exceeded when AC testing voltage is applied.

→ Test the device with DC voltage when you carry out the high-voltage test required by law. The voltage to be used corresponds to the peak value of the AC voltage required by the standard.

What has to be tested?	How to test?	Frequency	Which measure?
Check the protective casing against accidental contact for damage and to ensure that it is intact	Visual inspection	At least every 6 months	Repair or replacement of the device
Check the device for damage to blades and housing	Visual inspection	At least every 6 months	Replacement of the device
Mounting the connection lines	Visual inspection	At least every 6 months	Fasten
Mounting of protective earth connection	Visual inspection	At least every 6 months	Fasten
Check the insulation of the wires for damage	Visual inspection	At least every 6 months	Replace wires
Impeller for wear/deposits/ corrosion and damage	Visual inspection	At least every 6 months	Clean impeller or replace device
Abnormal bearing noise	acoustic	At least every 6 months	Replace device

## 6.3 Disposal

For ebm-papst, environmental protection and resource preservation are top priority corporate goals.

ebm-papst operates an environmental management system which is certified in accordance with ISO 14001 and rigorously implemented around the world on the basis of German standards.

Right from the development stage, ecological design, technical safety and health protection are fixed criteria.

The following section contains recommendations for ecological disposal of the product and its components.





Item no. 53670-5-9970 · ENG · Revision 230387 · Release 2021-03-29 · Page 10 / 11

ebm-papst Mulfingen GmbH & Co. KG · Bachmühle 2 · D-74673 Mulfingen · Phone +49 (0) 7938 81-0 · Fax +49 (0) 7938 81-110 · info1@de.ebmpapst.com · www.ebmpapst.com

6.3.1 Country-specific legal requirements



## NOTE

**Country-specific legal requirements** Always observe the applicable country-specific legal regulations with regard to the disposal of products or waste occurring in the various phases of the life cycle. The corresponding disposal standards are also to be heeded.

## 6.3.2 Disassembly

Disassembly of the product must be performed or supervised by qualified personnel with the appropriate technical knowledge. The product is to be disassembled into suitable components for disposal employing standard procedures for motors.



### WARNING

# Heavy parts of the product may drop off. Some of the product components are heavy. These components could drop off during disassembly.

This can result in fatal or serious injury and material damage.

→ Secure components before unfastening to stop them falling.

## 6.3.3 Component disposal

The products are mostly made of steel, copper, aluminium and plastic. Metallic materials are generally considered to be fully recyclable. Separate the components for recycling into the following categories:

- Steel and iron
- Aluminium
- Non-ferrous metal, e.g. motor windings
- Plastics, particularly with brominated flame retardants, in accordance with marking
- Insulating materials
- Cables and wires
- Electronic scrap, e.g. circuit boards

Only ferrite magnets and not rare earth magnets are used in external rotor motors from ebm-papst Mulfingen GmbH & Co. KG.

⇒ Ferrite magnets can be disposed of in the same way as normal iron and steel.

Electrical insulating materials on the product, in cables and wires are made of similar materials and are therefore to be treated in the same manner.

The materials concerned are as follows:

- Miscellaneous insulators used in the terminal box
- Power lines
- Cables for internal wiring
- Electrolytic capacitors

Dispose of electronic components employing the proper procedures for electronic scrap.



→ Please contact ebm-papst for any other questions on disposal.



ranslation of the original operating instri