CPTICON Laser Scan Engine MDL 1000



This manual provides specifications for the MDL 1000 laser scan engine.

Specifications Manual



All information subject to change without notice.

Document History

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SUPPORT

USA Europe

Phone: 800-636-0090

Email: support@opticonusa.com Email: support@opticon.com

Web: www.opticonusa.com Web: www.opticon.com



Contents

1.	Abstract	5
2.	Overview	5
3.	Physical Features	5
	3.1. Dimensions	5
	3.2. Weight	5
4.	Environmental Specifications	6
	4.1. Operating Temperature and Humidity	6
	4.2. Storage Temperature and Humidity	6
	4.3. Ambient Light Immunity	6
5.	Electrical Specifications	7
	5.1. Absolute Maximum Ratings	7
	5.2. Electrical Characteristics	7
	5.3. Power Mode Transition	8
6.	Optical Specifications	9
	6.1. Laser Scan Specifications	9
	6.1.1. Tilt of Laser Scan Line	9
	6.1.2. Curvature of Scan	9
7.	Technical Specifications	. 10
	7.1. Print Contrast Signal (PCS)	. 10
	7.2. Scan Area and Resolution	. 11
	7.2.1. Depth of Field	11
	7.3. Pitch, Skew, and Tilt	. 12
	7.4. Curvature	. 13
8.	Interface Specifications	. 14
	8.1. Interface Connector	. 14
	8.2. Interface Circuit	. 15
9.	Serial Number	. 17
10.	Packaging Specifications	. 18
11.	Durability	. 19
	11.1. Electrical Noise	. 19
	11.2. Shock	. 19
	11.3. Vibration Strength	. 19
12.	Reliability	
	Regulatory Compliance	
	13.1. Laser Safety	



13.2. RoHS	20
14. Safety	20
14.1. Shock	20
14.2. Temperature Conditions	20
14.3. Foreign Materials	20
14.4. Other	20
45.55	24
15. Mechanical Drawing	21
Table of Figures	
Table of Figures Figure 1: Current waveform	8
Table of Figures	8 8
Table of Figures Figure 1: Current waveform	
Table of Figures Figure 1: Current waveform	
Table of Figures Figure 1: Current waveform	
Table of Figures Figure 1: Current waveform	
Table of Figures Figure 1: Current waveform	



1. Abstract

This manual provides specifications for the MDL 1000 laser scan engine.

2. Overview

The MDL 1000 laser scan engine is a compact laser barcode scan engine which can be installed in various handheld products, such as a cellular terminal. When scanning a target at the closest point, it has the ability to scan up to 44 mm wide at an angle of 44°. The use of a short-wavelength red laser beam enhances visibility when scanning lines.

A decoder is built into the MDL 1000 that enables this scan engine to decode barcodes after scanning and output the information using serial communication.

The MDL 1000 complies with the Restriction of Hazardous Substances (RoHS).

3. Physical Features

3.1. Dimensions

W 28.0 x D 18.0 x H 8.0 mm

3.2. Weight

10 g (max.)



4. Environmental Specifications

4.1. Operating Temperature and Humidity

Temperature: -20° C to 65° C Humidity: 5% to 90% RH

4.2. Storage Temperature and Humidity

Temperature: -30° C to 70° C Humidity: 5% to 90% RH

4.3. Ambient Light Immunity

Decoding performance is guaranteed when the range of illumination on a barcode surface is between zero and the following values:

Incandescent light 4,000 lx

Fluorescent light 4,000 lx (excluding high-frequency lighting)

Sunlight 80,000 lx

Conditions

Barcode Sample: OPTOELECTRONICS Test Sample

PCS: 0.9

Resolution: 0.25 mm

Symbology: 9-digit Code 39

Quiet zone: 10 mm

N/W ratio: 1:2.5

Distance: 150 mm

Angle (see note below): $\alpha = 0^{\circ} \beta = 15^{\circ} \gamma = 0^{\circ}$

Curvature: $R = \infty$ Power supply voltage: 3.3 V

Direct light or specular reflection from a light source should be prevented from entering the acceptance area.

Note: α , β and γ respectively represent pitch, skew and tilt. Please see section 7 for how these values are defined.



5. Electrical Specifications

5.1. Absolute Maximum Ratings

Parameter	Symbol	Value	Unit
Power supply voltage (V _{CC} to GND)	Vcc	3.9	V
Input voltage	V _{IN}	-0.3 to V _{cc} +0.3	V

5.2. Electrical Characteristics

Electrical characteristics: V_{CC} =3.3 V, Ta=25° C

It	em	Symbol	Conditions	Min	Тур	Max	Unit
Operating Voltage		V _{CC}		3.0	_	3.6	V
Operatin	g Current 1	I _{OP1}	READ State	_	110	125	mA
Operatin	g Current 2	I _{OP2}	READ State		95	110	mA
Idle	Current	I _{IDL}	IDLE State	_	30	40	mA
Aiming	g Current	I _{AIM}	AIMING State	_	50	65	mA
Low Pov	ver Current	I _{LOW}	Low Power State	_	_	1400	uA
Rush Cı	ırrent Peak	I _{PEEK}		_	500	1000	mA
Input Voltage	High	V _{IH}		V _{CC} x 0.8	_	_	V
	Low	V _{IL}		_	_	V _{CC} x 0.2	V
0.1	High	V _{OH}	I _{OH} < 8mA	V _{CC} -0.6	_	_	V
Output Voltage (Decode LED)	High (Low Power State)	V _{OH}	I _{OH} < 5uA	V _{CC} -0.6	_	_	V
	Low	V _{OL}	I _{OL} < 8mA	_	_	0.4	V
0 1 11/1	High	V _{OH}	I _{OH} < 4mA	V _{CC} -0.6	_	_	V
Output Voltage (Txd, RTS)	High (Low Power State)	V _{OH}	I _{OH} < 5uA	V _{CC} -0.6	_	_	V
	Low	V _{OL}	ly < 4mA	_	_	0.4	V
Output Voltage (Power Down)	High (Low Power State)	V _{OH}	I _{OH} < 5uA	V _{CC} -0.6	_	_	V
	Low	V _{OL}	I _{OL} < 4mA	_	_	0.4	V
lm · · t	Current	I _{IN}	V _{IN} = 3.3V	_	_	-10	μΑ
input	Input Current		V _{IN} = 0V	_	_	50	μΑ



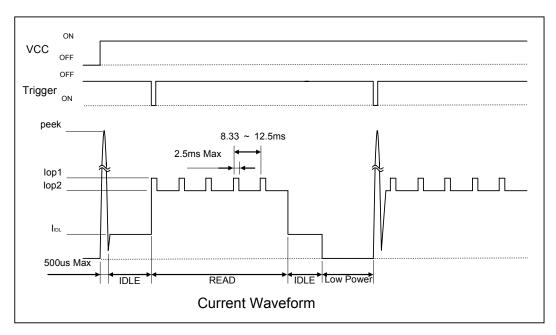


Figure 1: Current waveform

5.3. Power Mode Transition

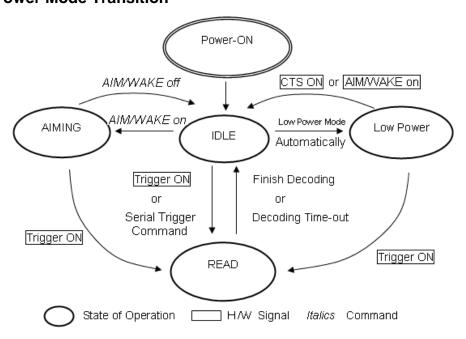


Figure 2: Current waveform

When in low power mode, the state of operation changes automatically from "Power On" to "Low Power".

If there is a transition to the "IDLE" state by enabling "CTS ON" or "WAKE ON" in "Low Power Mode," it will automatically go back to the "Low Power" state in a second unless transitioning to another mode.



6. Optical Specifications

6.1. Laser Scan Specifications

Parameter	Specification	Unit
Light-emitting element	Red laser diode	-
Emission wavelength	650 ±10 (25° C)	nm
Light output	1.0 or less	mW
Scanning method	Bi-directional scanning	-
Scanning speed	100 ±20	scans/s
Scan angle	Scan angle: 54 ±5	0
	Read angle: 44 (Min)	0

6.1.1. Tilt of Laser Scan Line

Maximum tilt between both ends of laser scan line: Less than 1.2° upward tilt from the scan origin.

Maximum of 3.1 mm when measured at a point 150 mm away from the scan origin. (The skew angle of this measurement was zero degrees.)

Measurement was done from the center of scan line.

6.1.2. Curvature of Scan

Maximum gap between the straight line connecting both ends of the laser scan line and the actual laser scan line: Less than 1.27° curvature from the scan origin.

Maximum of 3.3 mm curvature when measured at a point 150 mm away from the scan origin. (The skew angle of this measurement was zero degrees.)

Measurement was done from the center of scan line.

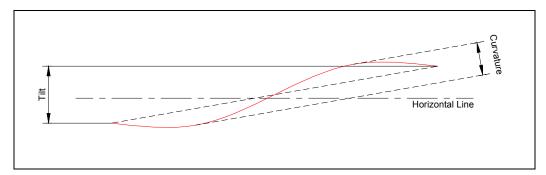


Figure 3: Laser scan tilt and curvature



7. Technical Specifications

The conditions for technical specifications are as follows, unless otherwise specified in each section.

Conditions

Ambient temperature and humidity Room temperature and room humidity

(5 to 35° C / 45% to 85% RH)

Ambient light 500 to 900 lx (excluding high-frequency lighting)

Background Barcode = black

Space = white Margin = white

Background of label = black

Power supply voltage 3.3 V

Decoding test Approve the performance when decoding is

successful in all ten tests.

(Decoding is deemed successful when completed

in 0.5 seconds or less.)

7.1. Print Contrast Signal (PCS)

0.45 or higher (over 70% of reflectivity of space and quiet zone).

Reflectance of white bar - Reflectance of black bar

Reflectance of white bar

Scanning performance may decline if dirt or scratches mar the optical window. Keep the optical window clean.



7.2. Scan Area and Resolution

7.2.1. Depth of Field

The depth of the decoding field is measured from the edge of the exit window. The decoding area is rectilinear near the exit window and expands in an arc centered on a virtual reference point in the distance.

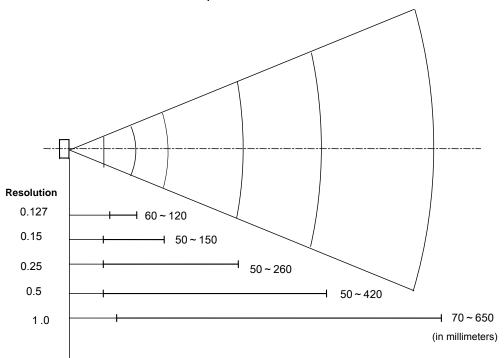


Figure 4: The depth of a decoding field.

Conditions

Barcode Sample: OPTOELECTRONICS Test Sample

N/W Ratio 1:2.5

Angle $\alpha = 0^{\circ}, \beta = 15^{\circ}, \gamma = 0^{\circ}$

Curvature R = ∞

Resolution	Symbology	PCS	Quiet Zone	Digits
1.0 mm	Code 39	0.9	25 mm	1
0.5 mm	Code 39	0.9	18 mm	3
0.25 mm	Code 39	0.9	10 mm	8
0.15 mm	Code 39	0.9	7 mm	10
0.127 mm	Code 39	0.9	5 mm	4



7.3. Pitch, Skew, and Tilt

Pitch angle: $\alpha = \pm 35^{\circ}$

Skew angle: $\beta = \pm 50^{\circ}$ (Excluding dead zone)

Dead zone: $\beta = \pm 8^{\circ}$ (There are some areas in which decoding fails due to specular

reflection)

Tilt Angle: $\gamma = \pm 20^{\circ}$

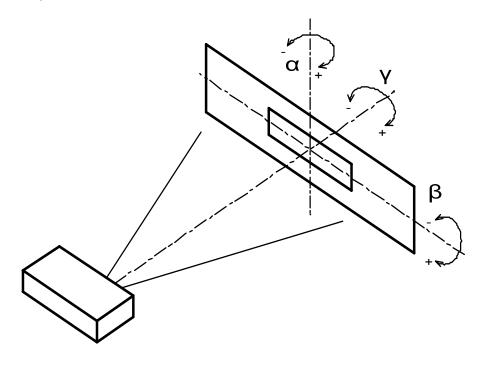


Figure 5: Pitch, skew, and tilt

Conditions

Barcode Sample: OPTOELECTRONICS Test Sample

Distance 110 mm from the exit window

Label Pitch, Skew Angle, Dead Zone

PCS = 0.9, Resolution = 0.25 mm, Symbology = 9-digit Code 39,

Quiet Zone = 10 mm, N/W Ratio = 1:2.5

Tilt Angle

PCS = 0.9, Resolution = 0.26 mm, Symbology = 13-digit JAN, Quiet Zone = 10 mm

Angle Curvature: $R = \infty$, Skew Angle = $\beta + 15^{\circ}$ (for measuring Pitch Angle and Tilt Angle)



7.4. Curvature

With 8-digit JAN/UPC/EAN barcodes, decoding performance is guaranteed when R≥15 mm.

With 13-digit JAN/UPC/EAN barcodes, decoding performance is guaranteed when R≥20 mm.

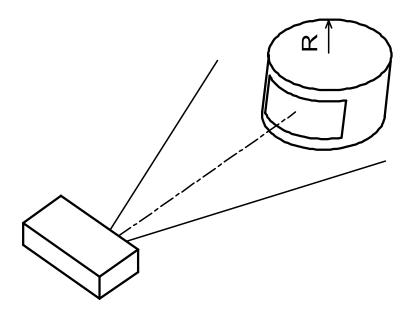


Figure 6: Curvature

Conditions

Barcode Sample: OPTOELECTRONICS Test Sample

PCS = 0.9, Resolution = 0.26 mm, Quiet Zone = 10 mm

Distance 110 mm from the edge of the exit window

Angle Skew Angle $\beta = +15^{\circ}$



8. Interface Specifications

8.1. Interface Connector

Signal	Pin No.	I/O	Features	
TEST	1	I	Input for the Test: High or Open = Normal Oper Maintenance Mode *	ation, Low =
VCC	2	_	Power Supply: DC 3.0V to 3.6V	
GND	3	_	Ground	
Rxd	4	I	Input Serial Data, CMOS Logic Level	
Txd	5	0	Output Serial Data, CMOS Logic Level	
CTS	6	I	Clear to Send, CMOS Logic Level	
RTS	7	0	Request to Send, CMOS Logic Level	
Power Down	8	0	Power Down Output, CMOS Logic Level High = Low Power St	
Buzzer	9	0	Buzzer Control Pulse Output, CMOS Logic Leve On	el Low = Buzzer
Decode LED	10	0	LED Output, CMOS Logic Level On	Low = LED
Aim/Wake	11	I	Aiming / Wakeup Input, CMOS Logic Level Aim/Wake	Low =
Trigger	12	I	Trigger Input, CMOS Logic Level Trigger	Low =

Connector used was produced by KYOCERA ELCO Corporation.

Product No. 04 6238 012 0 1 0 883+

12 pin 0.5 mm pitch FFC connector Bottom contact (Gold-plated terminal)



8.2. Interface Circuit

Pin No.	Signal	Circuitry
1	Test Terminal High = Normal Operation Mode Low = Maintenance Mode	TEST
2	VCC	_
3	GND	
4	Rxd Input	VCC 100K
5	Txd Output	VCC 100K Txd
6	CTS Input	VCC 100K
7	RTS Output	VCC 100K RTS



Pin No.	Signal	Circuitry
8	Power Down Output High = Low Power State	VCC 100K Power Down
9	Buzzer Output High = OFF Low = ON	VCC 100K Buzzer
10	Decode LED Output High = OFF Low = ON	VCC 100K Decode LED Power Down
11	Aim/Wake Input Low = Aim / Wake	Aim / Wake
12	Trigger Input Low = Trigger	Trigger Trigger



9. Serial Number

The serial number shown below is affixed to the MDL 1000.



Figure 7: Serial number diagram

Uppercase: Management Barcodes

(Symbology: Code 39, resolution: 0.12 to 0.2, N/W ratio = 1:2.5 to 1:3)

Lowercase: Model names, serial numbers (The height of the letters is 1.2 ± 0.3) *Serial number starts from 0000001 and is in order regardless of the lot number.



10. Packaging Specifications

Size of the package after assembly: W 355 x D 290 x H 185 mm

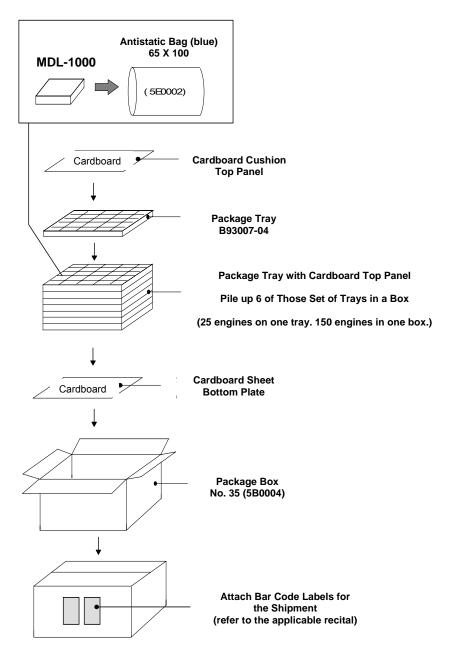


Figure 8: Packaging

Note: The "RO" mark labeled on the package tray or package box guarantees that the applicable product has passed our test of RoHS restrictions compliance (the restriction of the use of certain hazardous substances in electrical and electronic equipment, 2002/95 EC). However, this document does **not** have any legal weight in the European Union.



11. Durability

11.1. Electrical Noise

No malfunction occurred when sinusoidal electrical noise (50 Hz -100 kHz, < 0.1Vp-p) was added to a power supply line.

Conditions

Barcode Sample: OPTOELECTRONICS Test Sample

PCS	0.9
Resolution	0.25 mm
Symbology	9-digit Code 39
Quiet Zone	10 mm
N/W Ratio	1:2.5
Distance	150 mm
Angle	$\alpha = 0^{\circ} \beta = 15^{\circ} \gamma = 0^{\circ}$
Curvature	R = ∞
Power Supply Voltage	3.3 V

11.2. Shock

No malfunction occurred after the following drop test.

Drop Test: Fixed an MDL 1000 inside a dummy case and dropped it on its top, bottom, front, back, left, right, top-left, top-right, bottom-left and bottom-right sides from 1.8 meters above a concrete floor. Repeated this routine ten times

11.3. Vibration Strength

No malfunction occurred after the following vibration test.

Vibration test: Increase the frequency of the vibration from 12 Hz to 200 Hz with accelerated velocity 32.3 m/s^2 (3.3G) for 60 minutes in non-operating state. Repeated this routine for 2 hours to X direction, 2 hours to Y direction, and 4 hours to Z direction.

12. Reliability

MTBF (Mean Time Between Failures) of this product except for the laser diode and the scan unit is 30.000 hours.

Life cycle of the laser diode is 10,000 hours and that of the scan unit is also 10,000 hours.

The estimate of MTBF and product life cycle is based on standard operation of the product within the recommended temperature range and without extreme electronic or mechanical shock.



13. Regulatory Compliance

13.1. Laser Safety

The scan engine emits laser beams.

JIS C6802: 2005: Laser class 2 IEC60825-1+A2:2001 Class 2

FDA CDRH Laser class II. Complies with 21 CFR 1040.10 and 1040.11 except for deviations pursuant to laser notice No. 50 dated June 24, 2007.

Class II laser devices are not considered to be hazardous when used for their intended purpose. Avoid staring into the laser beam.

13.2. RoHS

RoHS: The restriction of the use of certain hazardous substances in electrical and electronic equipment, 2002/95 EC.

14. Safety

Handle this product carefully. Do not deliberately subject it to any of the following.

14.1. Shock

Do not throw or drop the scanner.

Do not place heavy objects on the cables.

14.2. Temperature Conditions

Do not use the scan engine at temperatures outside the specified range.

Do not pour boiling water on the scanner.

Do not throw the scan engine into the fire.

Do not forcibly bend the cables at low temperatures.

14.3. Foreign Materials

Do not immerse the scan engine in liquids.

Do not subject the scan engine to chemicals.

14.4. Other

Do not plug/unplug the connectors before disconnecting the power.

Do not disassemble this product.

Do not place the product near a radio or a TV receiver, as the scan engine may cause reception problems.

The scan engine may be damaged by voltage drops.

The scan engine may not perform properly in environments when placed near a flickering light, such as a computer monitor, television, etc.



15. Mechanical Drawing

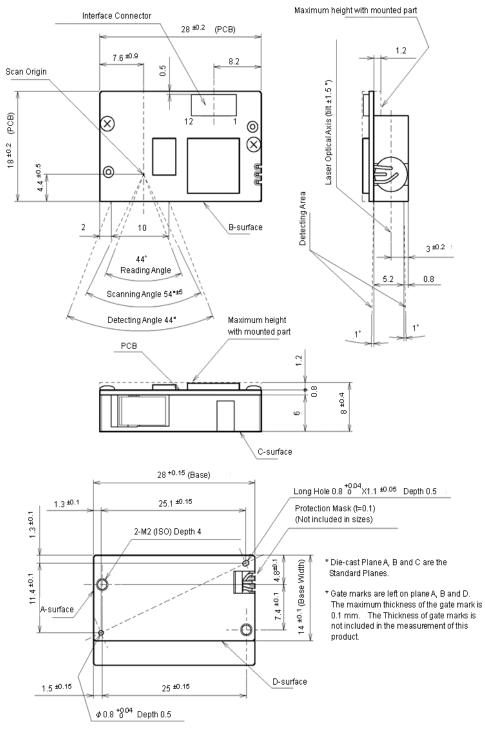


Figure 9: Mechanical drawing