### **Features**

- Incorporates the ARM7TDMI® ARM® Thumb® Processor
  - High-performance 32-bit RISC Architecture
  - High-density 16-bit Instruction Set
  - Leader in MIPS/Watt
  - EmbeddedICE<sup>™</sup> In-circuit Emulation, Debug Communication Channel Support
- Internal High-speed Flash
  - 512 Kbytes (SAM7S512) Organized in Two Contiguous Banks of 1024 Pages of 256 Bytes (Dual Plane)
  - 256 Kbytes (SAM7S256) Organized in 1024 Pages of 256 Bytes (Single Plane)
  - 128 Kbytes (SAM7S128) Organized in 512 Pages of 256 Bytes (Single Plane)
  - 64 Kbytes (SAM7S64) Organized in 512 Pages of 128 Bytes (Single Plane)
  - 32 Kbytes (SAM7S321/32) Organized in 256 Pages of 128 Bytes (Single Plane)
  - 16 Kbytes (SAM7S161/16) Organized in 256 Pages of 64 Bytes (Single Plane)
  - Single Cycle Access at Up to 30 MHz in Worst Case Conditions
  - Prefetch Buffer Optimizing Thumb Instruction Execution at Maximum Speed
  - Page Programming Time: 6 ms, Including Page Auto-erase, Full Erase Time: 15 ms
  - 10,000 Write Cycles, 10-year Data Retention Capability, Sector Lock Capabilities,
     Flash Security Bit
  - Fast Flash Programming Interface for High Volume Production
- Internal High-speed SRAM, Single-cycle Access at Maximum Speed
  - 64 Kbytes (SAM7S512/256)
  - 32 Kbytes (SAM7S128)
  - 16 Kbytes (SAM7S64)
  - 8 Kbytes (SAM7S321/32)
  - 4 Kbytes (SAM7S161/16)
- Memory Controller (MC)
  - Embedded Flash Controller, Abort Status and Misalignment Detection
- Reset Controller (RSTC)
  - Based on Power-on Reset and Low-power Factory-calibrated Brown-out Detector
  - Provides External Reset Signal Shaping and Reset Source Status
- Clock Generator (CKGR)
  - Low-power RC Oscillator, 3 to 20 MHz On-chip Oscillator and one PLL
- Power Management Controller (PMC)
  - Software Power Optimization Capabilities, Including Slow Clock Mode (Down to 500 Hz) and Idle Mode
  - Three Programmable External Clock Signals
- Advanced Interrupt Controller (AIC)
  - Individually Maskable, Eight-level Priority, Vectored Interrupt Sources
  - Two (SAM7S512/256/128/64/321/161) or One (SAM7S32/16) External Interrupt Source(s) and One Fast Interrupt Source, Spurious Interrupt Protected
- Debug Unit (DBGU)
  - 2-wire UART and Support for Debug Communication Channel interrupt,
     Programmable ICE Access Prevention
  - Mode for General Purpose 2-wire UART Serial Communication
- Periodic Interval Timer (PIT)
  - 20-bit Programmable Counter plus 12-bit Interval Counter
- Windowed Watchdog (WDT)
  - 12-bit key-protected Programmable Counter
  - Provides Reset or Interrupt Signals to the System



# AT91SAM ARM-based Flash MCU

SAM7S512 SAM7S256 SAM7S128 SAM7S64 SAM7S321 SAM7S32 SAM7S161 SAM7S16 Summary

**NOTE:** This is a summary document. The complete document is available on the Atmel website at www.atmel.com.







- Counter May Be Stopped While the Processor is in Debug State or in Idle Mode
- Real-time Timer (RTT)
  - 32-bit Free-running Counter with Alarm
  - Runs Off the Internal RC Oscillator
- One Parallel Input/Output Controller (PIOA)
  - Thirty-two (SAM7S512/256/128/64/321/161) or twenty-one (SAM7S32/16) Programmable I/O Lines Multiplexed with up to Two Peripheral I/Os
  - Input Change Interrupt Capability on Each I/O Line
  - Individually Programmable Open-drain, Pull-up resistor and Synchronous Output
- Eleven (SAM7S512/256/128/64/321/161) or Nine (SAM7S32/16) Peripheral DMA Controller (PDC) Channels
- One USB 2.0 Full Speed (12 Mbits per Second) Device Port (Except for the SAM7S32/16).
  - On-chip Transceiver, 328-byte Configurable Integrated FIFOs
- One Synchronous Serial Controller (SSC)
  - Independent Clock and Frame Sync Signals for Each Receiver and Transmitter
  - I2S Analog Interface Support, Time Division Multiplex Support
  - High-speed Continuous Data Stream Capabilities with 32-bit Data Transfer
- Two (SAM7S512/256/128/64/321/161) or One (SAM7S32/16) Universal Synchronous/Asynchronous Receiver Transmitters (USART)
  - Individual Baud Rate Generator, IrDA® Infrared Modulation/Demodulation
  - Support for ISO7816 T0/T1 Smart Card, Hardware Handshaking, RS485 Support
  - Full Modem Line Support on USART1 (SAM7S512/256/128/64/321/161)
- One Master/Slave Serial Peripheral Interface (SPI)
  - 8- to 16-bit Programmable Data Length, Four External Peripheral Chip Selects
- One Three-channel 16-bit Timer/Counter (TC)
  - Three External Clock Input and Two Multi-purpose I/O Pins per Channel (SAM7S512/256/128/64/321/161)
  - One External Clock Input and Two Multi-purpose I/O Pins for the first Two Channels Only (SAM7S32/16)
  - Double PWM Generation, Capture/Waveform Mode, Up/Down Capability
- One Four-channel 16-bit PWM Controller (PWMC)
- One Two-wire Interface (TWI)
  - Master Mode Support Only, All Two-wire Atmel EEPROMs and I<sup>2</sup>C Compatible Devices Supported (SAM7S512/256/128/64/321/32)
  - Master, Multi-Master and Slave Mode Support, All Two-wire Atmel EEPROMs and I<sup>2</sup>C Compatible Devices Supported (SAM7S161/16)
- One 8-channel 10-bit Analog-to-Digital Converter, Four Channels Multiplexed with Digital I/Os
- SAM-BA<sup>™</sup> Boot Assistant
  - Default Boot program
  - Interface with SAM-BA Graphic User Interface
- IEEE® 1149.1 JTAG Boundary Scan on All Digital Pins
- 5V-tolerant I/Os, including Four High-current Drive I/O lines, Up to 16 mA Each (SAM7S161/16 I/Os Not 5V-tolerant)
- Power Supplies
  - Embedded 1.8V Regulator, Drawing up to 100 mA for the Core and External Components
  - 3.3V or 1.8V VDDIO I/O Lines Power Supply, Independent 3.3V VDDFLASH Flash Power Supply
  - 1.8V VDDCORE Core Power Supply with Brown-out Detector
- Fully Static Operation: Up to 55 MHz at 1.65V and 85. C Worst Case Conditions
- Available in 64-lead LQFP Green or 64-pad QFN Green Package (SAM7S512/256/128/64/321/161) and 48-lead LQFP Green or 48-pad QFN Green Package (SAM7S32/16)

## 1. Description

Atmel's SAM7S is a series of low pincount Flash microcontrollers based on the 32-bit ARM RISC processor. It features a high-speed Flash and an SRAM, a large set of peripherals, including a USB 2.0 device (except for the SAM7S32 and SAM7S16), and a complete set of system functions minimizing the number of external components. The device is an ideal migration path for 8-bit microcontroller users looking for additional performance and extended memory.

The embedded Flash memory can be programmed in-system via the JTAG-ICE interface or via a parallel interface on a production programmer prior to mounting. Built-in lock bits and a security bit protect the firmware from accidental overwrite and preserves its confidentiality.

The SAM7S Series system controller includes a reset controller capable of managing the poweron sequence of the microcontroller and the complete system. Correct device operation can be monitored by a built-in brownout detector and a watchdog running off an integrated RC oscillator.

The SAM7S Series are general-purpose microcontrollers. Their integrated USB Device port makes them ideal devices for peripheral applications requiring connectivity to a PC or cellular phone. Their aggressive price point and high level of integration pushes their scope of use far into the cost-sensitive, high-volume consumer market.

# 1.1 Configuration Summary of the SAM7S512, SAM7S256, SAM7S128, SAM7S64, SAM7S321, SAM7S32, SAM7S161 and SAM7S16

The SAM7S12, SAM7S256, SAM7S128, SAM7S64, SAM7S321, SAM7S32, SAM7S161 and SAM7S16 differ in memory size, peripheral set and package. Table 1-1 summarizes the configuration of the six devices.

Except for the SAM7S32/16, all other SAM7S devices are package and pinout compatible.

**Table 1-1.** Configuration Summary

Device	Flash	TWI	Flash Organization	SRAM	USB Device Port	USART	External Interrupt Source	PDC Channels	TC Channels	I/O 5V Tolerant	I/O Lines	Package
SAM7S512	512 Kbytes	Master	dual plane	64 Kbytes	1	2 <sup>(1)</sup> (2)	2	11	3	Yes	32	LQFP/ QFN 64
SAM7S256	256 Kbytes	Master	single plane	64 Kbytes	1	2 <sup>(1)</sup> (2)	2	11	3	Yes	32	LQFP/ QFN 64
SAM7S128	128 Kbytes	Master	single plane	32 Kbytes	1	2 <sup>(1)</sup> (2)	2	11	3	Yes	32	LQFP/ QFN 64
SAM7S64	64 Kbytes	Master	single plane	16 Kbytes	1	2 <sup>(2)</sup>	2	11	3	Yes	32	LQFP/ QFN 64
SAM7S321	32 Kbytes	Master	single plane	8 Kbytes	1	2 <sup>(2)</sup>	2	11	3	Yes	32	LQFP/ QFN 64
SAM7S32	32 Kbytes	Master	single plane	8 Kbytes	not present	1	1	9	3 <sup>(3)</sup>	Yes	21	LQFP/ QFN 48
SAM7S161	16 Kbytes	Master/ Slave	single plane	4 Kbytes	1	2 <sup>(2)</sup>	2	11	3	No	32	LQFP
SAM7S16	16 Kbytes	Master/ Slave	single plane	4 Kbytes	not present	1	1	9	3 <sup>(3)</sup>	No	21	LQFP/ QFN 48

Notes: 1. Fractional Baud Rate.

- 2. Full modem line support on USART1.
- 3. Only two TC channels are accessible through the PIO.





## 2. Block Diagram

Figure 2-1. SAM7S512/256/128/64/321/161 Block Diagram

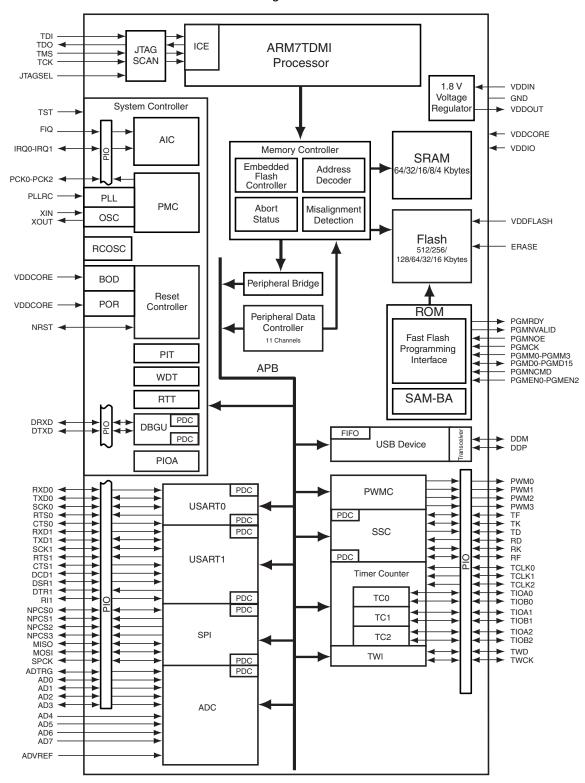
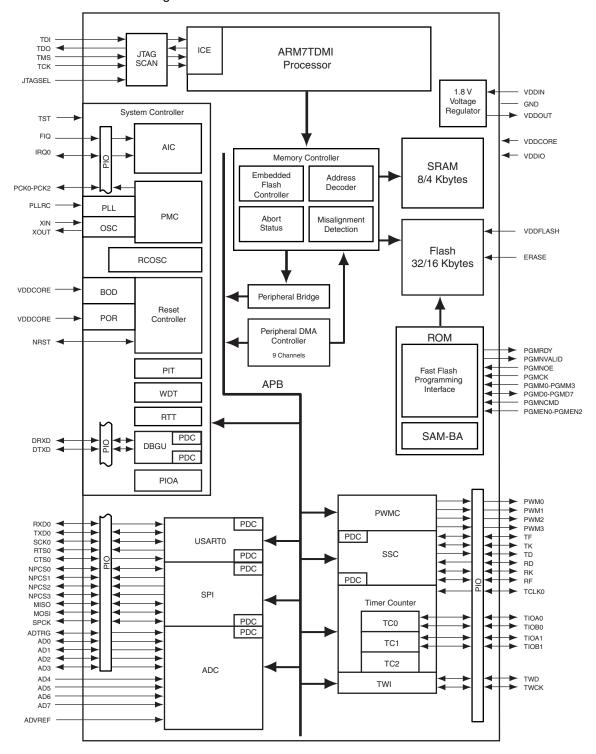


Figure 2-2. SAM7S32/16 Block Diagram







# 3. Signal Description

 Table 3-1.
 Signal Description List

Function	Type	Active Level	Comments
Voltage and ADC Regulator Power Supply	Power		3.0 to 3.6V
Voltage Regulator Output	Power		1.85V nominal
Flash Power Supply	Power		3.0V to 3.6V
I/O Lines Power Supply	Power		3.0V to 3.6V or 1.65V to 1.95V
Core Power Supply	Power		1.65V to 1.95V
PLL	Power		1.65V to 1.95V
Ground	Ground		
Clocks, Oscilla	ators and PL	Ls	
Main Oscillator Input	Input		
Main Oscillator Output	Output		
PLL Filter	Input		
Programmable Clock Output	Output		
ICE an	d JTAG		
Test Clock	Input		No pull-up resistor
Test Data In	Input		No pull-up resistor
Test Data Out	Output		
Test Mode Select	Input		No pull-up resistor
JTAG Selection	Input		Pull-down resistor <sup>(1)</sup>
Flash I	Memory		
Flash and NVM Configuration Bits Erase Command	Input	High	Pull-down resistor <sup>(1)</sup>
Rese	t/Test		
Microcontroller Reset	I/O	Low	Open-drain with pull-Up resistor
Test Mode Select	Input	High	Pull-down resistor <sup>(1)</sup>
Debu	g Unit	1	
Debug Receive Data	Input		
Debug Transmit Data	Output		
A	IC	1	
External Interrupt Inputs	Input		IRQ1 not present on SAM7S32/16
Fast Interrupt Input	Input		
Р	IO	1	
Parallel IO Controller A	I/O		Pulled-up input at reset PA0 - PA20 only on SAM7S32/16
	Voltage and ADC Regulator Power Supply Input  Voltage Regulator Output  Flash Power Supply  I/O Lines Power Supply  Core Power Supply  PLL  Ground  Clocks, Oscillat  Main Oscillator Input  Main Oscillator Output  PLL Filter  Programmable Clock Output  ICE an  Test Clock  Test Data In  Test Data Out  Test Mode Select  JTAG Selection  Flash I  Flash and NVM Configuration Bits Erase Command  Rese  Microcontroller Reset  Test Mode Select  Debug Receive Data  Debug Transmit Data  A  External Interrupt Inputs  Fast Interrupt Input	Voltage and ADC Regulator Power Supply Input Voltage Regulator Output Power Flash Power Supply Power I/O Lines Power Supply Power Core Power Supply Power PLL Power Ground Ground Clocks, Oscillators and PL Main Oscillator Input Input Main Oscillator Output Output PLL Filter Input Programmable Clock Output Output Test Clock Input Test Data In Input Test Data Out Output Test Mode Select Input JTAG Selection Input Flash Memory Flash and NVM Configuration Bits Erase Command Reset/Test Microcontroller Reset I/O Test Mode Select Input Debug Unit Debug Transmit Data Output External Interrupt Inputs Input Fast Input Fast Input Fast Input Debug Transmit Data Input Fast Input Fast Input Fast Input Fast Interrupt Inputs Input Fast Input Input Fast Input Fast Input Fast Interrupt Input Input Fast Input	Function

# ■ SAM7S Series Summary

 Table 3-1.
 Signal Description List (Continued)

			Active	
Signal Name	Function	Туре	Level	Comments
	USE	B Device Port		
DDM	USB Device Port Data -	Analog		not present on SAM7S32/16
DDP	USB Device Port Data +	Analog		not present on SAM7S32/16
	•	USART	•	
SCK0 - SCK1	Serial Clock	I/O		SCK1 not present on SAM7S32/16
TXD0 - TXD1	Transmit Data	I/O		TXD1 not present on SAM7S32/16
RXD0 - RXD1	Receive Data	Input		RXD1 not present on SAM7S32/16
RTS0 - RTS1	Request To Send	Output		RTS1 not present on SAM7S32/16
CTS0 - CTS1	Clear To Send	Input		CTS1 not present on SAM7S32/16
DCD1	Data Carrier Detect	Input		not present on SAM7S32/16
DTR1	Data Terminal Ready	Output		not present on SAM7S32/16
DSR1	Data Set Ready	Input		not present on SAM7S32/16
RI1	Ring Indicator	Input		not present on SAM7S32/16
	Synchrono	ous Serial Contro	ller	
TD	Transmit Data	Output		
RD	Receive Data	Input		
TK	Transmit Clock	I/O		
RK	Receive Clock	I/O		
TF	Transmit Frame Sync	I/O		
RF	Receive Frame Sync	I/O		
	Tir	mer/Counter	1	
TCLK0 - TCLK2	External Clock Inputs	Input		TCLK1 and TCLK2 not present on SAM7S32/16
TIOA0 - TIOA2	I/O Line A	I/O		TIOA2 not present on SAM7S32/16
TIOB0 - TIOB2	I/O Line B	I/O		TIOB2 not present on SAM7S32/16
	PW	M Controller	1	
PWM0 - PWM3	PWM Channels	Output		
		SPI	•	
MISO	Master In Slave Out	I/O		
MOSI	Master Out Slave In	I/O		
SPCK	SPI Serial Clock	I/O		
NPCS0	SPI Peripheral Chip Select 0	I/O	Low	
NPCS1-NPCS3	SPI Peripheral Chip Select 1 to 3	Output	Low	





 Table 3-1.
 Signal Description List (Continued)

Signal Name	Function	Туре	Active Level	Comments			
	Two-Wire Interface						
TWD	Two-wire Serial Data	I/O					
TWCK	Two-wire Serial Clock	I/O					
	Analog-to-Digital Converter						
AD0-AD3	Analog Inputs	Analog		Digital pulled-up inputs at reset			
AD4-AD7	Analog Inputs	Analog		Analog Inputs			
ADTRG	ADC Trigger	Input					
ADVREF	ADC Reference	Analog					
	Fast Flash Programming Interface						
PGMEN0-PGMEN2	Programming Enabling	Input					
PGMM0-PGMM3	Programming Mode	Input					
PGMD0-PGMD15	Programming Data	I/O		PGMD0-PGMD7 only on SAM7S32/16			
PGMRDY	Programming Ready	Output	High				
PGMNVALID	Data Direction	Output	Low				
PGMNOE	Programming Read	Input	Low				
PGMCK	Programming Clock	Input					
PGMNCMD	Programming Command	Input	Low				

Note: 1. Refer to Section 6. "I/O Lines Considerations" on page 14.

## 4. Package and Pinout

The SAM7S512/256/128/64/321 are available in a 64-lead LQFP or 64-pad QFN package.

The SAM7S161 is available in a 64-Lead LQFP package.

The SAM7S32/16 are available in a 48-lead LQFP or 48-pad QFN package.

## 4.1 64-lead LQFP and 64-pad QFN Package Outlines

Figure 4-1 and Figure 4-2 show the orientation of the 64-lead LQFP and the 64-pad QFN package. A detailed mechanical description is given in the section Mechanical Characteristics of the full datasheet.

Figure 4-1. 64-lead LQFP Package (Top View)

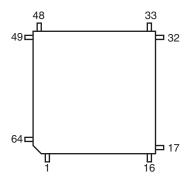
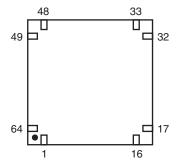


Figure 4-2. 64-pad QFN Package (Top View)





## 4.2 64-lead LQFP and 64-pad QFN Pinout

**Table 4-1.** SAM7S512/256/128/64/321/161 Pinout<sup>(1)</sup>

1	ADVREF
2	GND
3	AD4
4	AD5
5	AD6
6	AD7
7	VDDIN
8	VDDOUT
9	PA17/PGMD5/AD0
10	PA18/PGMD6/AD1
11	PA21/PGMD9
12	VDDCORE
13	PA19/PGMD7/AD2
14	PA22/PGMD10
15	PA23/PGMD11
16	PA20/PGMD8/AD3

GND
GIVE
VDDIO
PA16/PGMD4
PA15/PGMD3
PA14/PGMD2
PA13/PGMD1
PA24/PGMD12
VDDCORE
PA25/PGMD13
PA26/PGMD14
PA12/PGMD0
PA11/PGMM3
PA10/PGMM2
PA9/PGMM1
PA8/PGMM0
PA7/PGMNVALID

33	TDI
34	PA6/PGMNOE
35	PA5/PGMRDY
36	PA4/PGMNCMD
37	PA27/PGMD15
38	PA28
39	NRST
40	TST
41	PA29
42	PA30
43	PA3
44	PA2/PGMEN2
45	VDDIO
46	GND
47	PA1/PGMEN1
48	PA0/PGMEN0

49	TDO
50	JTAGSEL
51	TMS
52	PA31
53	TCK
54	VDDCORE
55	ERASE
56	DDM
57	DDP
58	VDDIO
59	VDDFLASH
60	GND
61	XOUT
62	XIN/PGMCK
63	PLLRC
64	VDDPLL

Note: 1. The bottom pad of the QFN package must be connected to ground.

## 4.3 48-lead LQFP and 48-pad QFN Package Outlines

Figure 4-3 and Figure 4-4 show the orientation of the 48-lead LQFP and the 48-pad QFN package. A detailed mechanical description is given in the section Mechanical Characteristics of the full datasheet.

Figure 4-3. 48-lead LQFP Package (Top View)

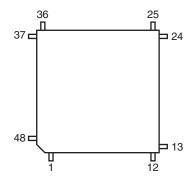
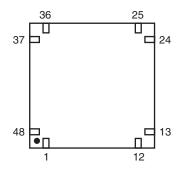


Figure 4-4. 48-pad QFN Package (Top View)



## 4.4 48-lead LQFP and 48-pad QFN Pinout

**Table 4-2.** SAM7S32/16 Pinout<sup>(1)</sup>

1	ADVREF		
2	GND		
3	AD4		
4	AD5		
5	AD6		
6	AD7		
7	VDDIN		
8	VDDOUT		
9	PA17/PGMD5/AD0		
10	PA18/PGMD6/AD1		
11	PA19/PGMD7/AD2		
12	PA20/AD3		

13	VDDIO
14	PA16/PGMD4
15	PA15/PGMD3
16	PA14/PGMD2
17	PA13/PGMD1
18	VDDCORE
19	PA12/PGMD0
20	PA11/PGMM3
21	PA10/PGMM2
22	PA9/PGMM1
23	PA8/PGMM0
24	PA7/PGMNVALID

25	TDI
26	PA6/PGMNOE
27	PA5/PGMRDY
28	PA4/PGMNCMD
29	NRST
30	TST
31	PA3
32	PA2/PGMEN2
33	VDDIO
34	GND
35	PA1/PGMEN1
36	PA0/PGMEN0

37	TDO
38	JTAGSEL
39	TMS
40	TCK
41	VDDCORE
42	ERASE
43	VDDFLASH
44	GND
45	XOUT
46	XIN/PGMCK
47	PLLRC
48	VDDPLL

Note: 1. The bottom pad of the QFN package must be connected to ground.





## 5. Power Considerations

## 5.1 Power Supplies

The SAM7S Series has six types of power supply pins and integrates a voltage regulator, allowing the device to be supplied with only one voltage. The six power supply pin types are:

- VDDIN pin. It powers the voltage regulator and the ADC; voltage ranges from 3.0V to 3.6V, 3.3V nominal.
- VDDOUT pin. It is the output of the 1.8V voltage regulator.
- VDDIO pin. It powers the I/O lines and the USB transceivers; dual voltage range is supported. Ranges from 3.0V to 3.6V, 3.3V nominal or from 1.65V to 1.95V, 1.8V nominal.
   Note that supplying less than 3.0V to VDDIO prevents any use of the USB transceivers.
- VDDFLASH pin. It powers a part of the Flash and is required for the Flash to operate correctly; voltage ranges from 3.0V to 3.6V, 3.3V nominal.
- VDDCORE pins. They power the logic of the device; voltage ranges from 1.65V to 1.95V,
   1.8V typical. It can be connected to the VDDOUT pin with decoupling capacitor. VDDCORE is required for the device, including its embedded Flash, to operate correctly.

During startup, core supply voltage (VDDCORE) slope must be superior or equal to 6V/ms.

 VDDPLL pin. It powers the oscillator and the PLL. It can be connected directly to the VDDOUT pin.

No separate ground pins are provided for the different power supplies. Only GND pins are provided and should be connected as shortly as possible to the system ground plane.

In order to decrease current consumption, if the voltage regulator and the ADC are not used, VDDIN, ADVREF, AD4, AD5, AD6 and AD7 should be connected to GND. In this case VDDOUT should be left unconnected.

### 5.2 Power Consumption

The SAM7S Series has a static current of less than 60  $\mu$ A on VDDCORE at 25°C, including the RC oscillator, the voltage regulator and the power-on reset. When the brown-out detector is activated, 20  $\mu$ A static current is added.

The dynamic power consumption on VDDCORE is less than 50 mA at full speed when running out of the Flash. Under the same conditions, the power consumption on VDDFLASH does not exceed 10 mA.

### 5.3 Voltage Regulator

The SAM7S Series embeds a voltage regulator that is managed by the System Controller.

In Normal Mode, the voltage regulator consumes less than 100  $\mu$ A static current and draws 100 mA of output current.

The voltage regulator also has a Low-power Mode. In this mode, it consumes less than 25  $\mu$ A static current and draws 1 mA of output current.

Adequate output supply decoupling is mandatory for VDDOUT to reduce ripple and avoid oscillations. The best way to achieve this is to use two capacitors in parallel: one external 470 pF (or 1 nF) NPO capacitor must be connected between VDDOUT and GND as close to the chip as possible. One external 2.2  $\mu$ F (or 3.3  $\mu$ F) X7R capacitor must be connected between VDDOUT and GND.

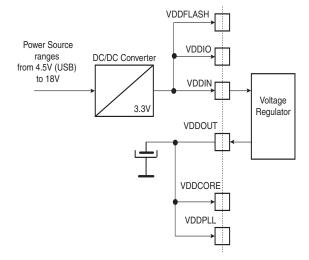
# **SAM7S Series Summary**

Adequate input supply decoupling is mandatory for VDDIN in order to improve startup stability and reduce source voltage drop. The input decoupling capacitor should be placed close to the chip. For example, two capacitors can be used in parallel: 100 nF NPO and  $4.7 \, \mu F$  X7R.

## 5.4 Typical Powering Schematics

The SAM7S Series supports a 3.3V single supply mode. The internal regulator is connected to the 3.3V source and its output feeds VDDCORE and the VDDPLL. Figure 5-1 shows the power schematics to be used for USB bus-powered systems.

Figure 5-1. 3.3V System Single Power Supply Schematic







## 6. I/O Lines Considerations

#### 6.1 JTAG Port Pins

TMS, TDI and TCK are schmitt trigger inputs. TMS and TCK are 5-V tolerant, TDI is not. TMS, TDI and TCK do not integrate a pull-up resistor.

TDO is an output, driven at up to VDDIO, and has no pull-up resistor.

The JTAGSEL pin is used to select the JTAG boundary scan when asserted at a high level. The JTAGSEL pin integrates a permanent pull-down resistor of about 15 k $\Omega$  to GND, so that it can be left unconnected for normal operations.

### 6.2 Test Pin

The TST pin is used for manufacturing test, fast programming mode or SAM-BA Boot Recovery of the SAM7S Series when asserted high. The TST pin integrates a permanent pull-down resistor of about 15 k $\Omega$  to GND, so that it can be left unconnected for normal operations.

To enter fast programming mode, the TST pin and the PA0 and PA1 pins should be tied high and PA2 tied to low.

To enter SAM-BA Boot Recovery, the TST pin and the PA0, PA1 and PA2 pins should be tied high for at least 10 seconds. Then a power cycle of the board is mandatory.

Driving the TST pin at a high level while PA0 or PA1 is driven at 0 leads to unpredictable results.

#### 6.3 Reset Pin

The NRST pin is bidirectional with an open drain output buffer. It is handled by the on-chip reset controller and can be driven low to provide a reset signal to the external components or asserted low externally to reset the microcontroller. There is no constraint on the length of the reset pulse, and the reset controller can guarantee a minimum pulse length. This allows connection of a simple push-button on the pin NRST as system user reset, and the use of the signal NRST to reset all the components of the system.

The NRST pin integrates a permanent pull-up resistor to VDDIO.

#### 6.4 ERASE Pin

The ERASE pin is used to re-initialize the Flash content and some of its NVM bits. It integrates a permanent pull-down resistor of about 15 k $\Omega$  to GND, so that it can be left unconnected for normal operations.

### 6.5 PIO Controller A Lines

- All the I/O lines PA0 to PA31on SAM7S512/256/128/64/321 (PA0 to PA20 on SAM7S32) are 5V-tolerant and all integrate a programmable pull-up resistor.
- All the I/O lines PA0 to PA31 on SAM7S161 (PA0 to PA20 on SAM7S16) are **not** 5V-tolerant and all integrate a programmable pull-up resistor.

Programming of this pull-up resistor is performed independently for each I/O line through the PIO controllers.

5V-tolerant means that the I/O lines can drive voltage level according to VDDIO, but can be driven with a voltage of up to 5.5V. However, driving an I/O line with a voltage over VDDIO while the programmable pull-up resistor is enabled will create a current path through the pull-up resis-

# **SAM7S Series Summary**

tor from the I/O line to VDDIO. Care should be taken, in particular at reset, as all the I/O lines default to input with the pull-up resistor enabled at reset.

## 6.6 I/O Line Drive Levels

The PIO lines PA0 to PA3 are high-drive current capable. Each of these I/O lines can drive up to 16 mA permanently.

The remaining I/O lines can draw only 8 mA.

However, the total current drawn by all the I/O lines cannot exceed 150 mA (100 mA for SAM7S32/16).





## 7. Processor and Architecture

#### 7.1 ARM7TDMI Processor

- RISC processor based on ARMv4T Von Neumann architecture
  - Runs at up to 55 MHz, providing 0.9 MIPS/MHz
- Two instruction sets
  - ARM® high-performance 32-bit instruction set
  - Thumb® high code density 16-bit instruction set
- Three-stage pipeline architecture
  - Instruction Fetch (F)
  - Instruction Decode (D)
  - Execute (E)

## 7.2 Debug and Test Features

- Integrated EmbeddedICE<sup>™</sup> (embedded in-circuit emulator)
  - Two watchpoint units
  - Test access port accessible through a JTAG protocol
  - Debug communication channel
- Debug Unit
  - Two-pin UART
  - Debug communication channel interrupt handling
  - Chip ID Register
- IEEE1149.1 JTAG Boundary-scan on all digital pins

## 7.3 Memory Controller

- Bus Arbiter
  - Handles requests from the ARM7TDMI and the Peripheral DMA Controller
- · Address decoder provides selection signals for
  - Three internal 1 Mbyte memory areas
  - One 256 Mbyte embedded peripheral area
- Abort Status Registers
  - Source, Type and all parameters of the access leading to an abort are saved
  - Facilitates debug by detection of bad pointers
- Misalignment Detector
  - Alignment checking of all data accesses
  - Abort generation in case of misalignment
- Remap Command
  - Remaps the SRAM in place of the embedded non-volatile memory
  - Allows handling of dynamic exception vectors
- Embedded Flash Controller
  - Embedded Flash interface, up to three programmable wait states

# **SAM7S Series Summary**

- Prefetch buffer, buffering and anticipating the 16-bit requests, reducing the required wait states
- Key-protected program, erase and lock/unlock sequencer
- Single command for erasing, programming and locking operations
- Interrupt generation in case of forbidden operation

## 7.4 Peripheral DMA Controller

- Handles data transfer between peripherals and memories
- Eleven channels: SAM7S512/256/128/64/321/161
- Nine channels: SAM7S32/16
  - Two for each USART
  - Two for the Debug Unit
  - Two for the Serial Synchronous Controller
  - Two for the Serial Peripheral Interface
  - One for the Analog-to-digital Converter
- · Low bus arbitration overhead
  - One Master Clock cycle needed for a transfer from memory to peripheral
  - Two Master Clock cycles needed for a transfer from peripheral to memory
- Next Pointer management for reducing interrupt latency requirements
- Peripheral DMA Controller (PDC) priority is as follows (from the highest priority to the lowest):

Receive	DBGU
Receive	USART0
Receive	USART1
Receive	SSC
Receive	ADC
Receive	SPI
Transmit	DBGU
Transmit	USART0
Transmit	USART1
Transmit	SSC
Transmit	SPI





## 8. Memories

#### 8.1 SAM7S512

- 512 Kbytes of Flash Memory, dual plane
  - 2 contiguous banks of 1024 pages of 256 bytes
  - Fast access time, 30 MHz single-cycle access in Worst Case conditions
  - Page programming time: 6 ms, including page auto-erase
  - Page programming without auto-erase: 3 ms
  - Full chip erase time: 15 ms
  - 10,000 write cycles, 10-year data retention capability
  - 32 lock bits, protecting 32 sectors of 64 pages
  - Protection Mode to secure contents of the Flash
- 64 Kbytes of Fast SRAM
  - Single-cycle access at full speed

## 8.2 SAM7S256

- 256 Kbytes of Flash Memory, single plane
  - 1024 pages of 256 bytes
  - Fast access time, 30 MHz single-cycle access in Worst Case conditions
  - Page programming time: 6 ms, including page auto-erase
  - Page programming without auto-erase: 3 ms
  - Full chip erase time: 15 ms
  - 10,000 write cycles, 10-year data retention capability
  - 16 lock bits, protecting 16 sectors of 64 pages
  - Protection Mode to secure contents of the Flash
- 64 Kbytes of Fast SRAM
  - Single-cycle access at full speed

#### 8.3 SAM7S128

18

- 128 Kbytes of Flash Memory, single plane
  - 512 pages of 256 bytes
  - Fast access time, 30 MHz single-cycle access in Worst Case conditions
  - Page programming time: 6 ms, including page auto-erase
  - Page programming without auto-erase: 3 ms
  - Full chip erase time: 15 ms
  - 10,000 write cycles, 10-year data retention capability
  - 8 lock bits, protecting 8 sectors of 64 pages
  - Protection Mode to secure contents of the Flash
- 32 Kbytes of Fast SRAM
  - Single-cycle access at full speed

### 8.4 SAM7S64

- 64 Kbytes of Flash Memory, single plane
  - 512 pages of 128 bytes
  - Fast access time, 30 MHz single-cycle access in Worst Case conditions
  - Page programming time: 6 ms, including page auto-erase
  - Page programming without auto-erase: 3 ms
  - Full chip erase time: 15 ms
  - 10,000 write cycles, 10-year data retention capability
  - 16 lock bits, protecting 16 sectors of 32 pages
  - Protection Mode to secure contents of the Flash
- 16 Kbytes of Fast SRAM
  - Single-cycle access at full speed

#### 8.5 SAM7S321/32

- 32 Kbytes of Flash Memory, single plane
  - 256 pages of 128 bytes
  - Fast access time, 30 MHz single-cycle access in Worst Case conditions
  - Page programming time: 6 ms, including page auto-erase
  - Page programming without auto-erase: 3 ms
  - Full chip erase time: 15 ms
  - 10,000 write cycles, 10-year data retention capability
  - 8 lock bits, protecting 8 sectors of 32 pages
  - Protection Mode to secure contents of the Flash
- 8 Kbytes of Fast SRAM
  - Single-cycle access at full speed

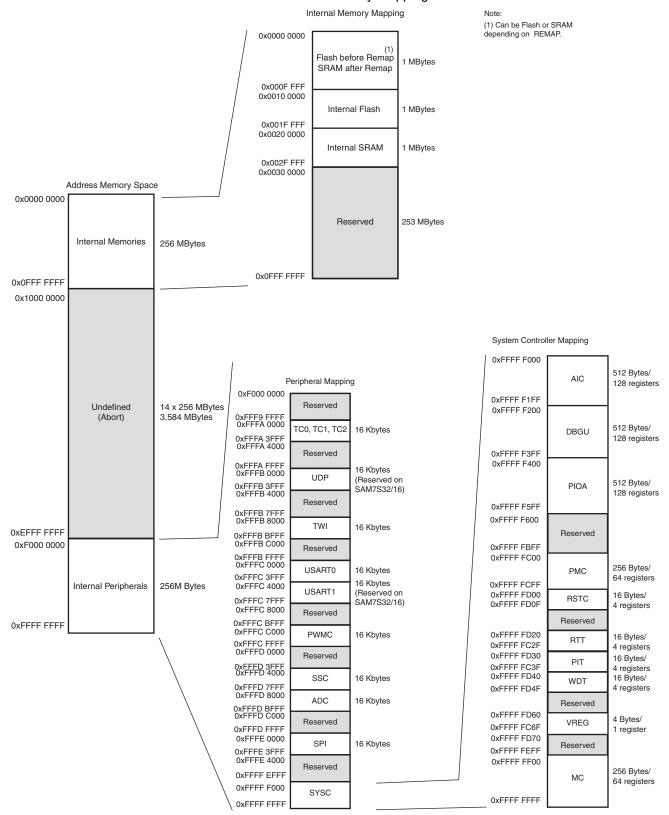
#### 8.6 SAM7S161/16

- 16 Kbytes of Flash Memory, single plane
  - 256 pages of 64 bytes
  - Fast access time, 30 MHz single-cycle access in Worst Case conditions
  - Page programming time: 6 ms, including page auto-erase
  - Page programming without auto-erase: 3 ms
  - Full chip erase time: 15 ms
  - 10,000 write cycles, 10-year data retention capability
  - 8 lock bits, protecting 8 sectors of 32 pages
  - Protection Mode to secure contents of the Flash
- 4 Kbytes of Fast SRAM
  - Single-cycle access at full speed





Figure 8-1. SAM SAM7S512/256/128/64/321/32/161/16 Memory Mapping



## 8.7 Memory Mapping

#### 8.7.1 Internal SRAM

- The SAM7S512 embeds a high-speed 64-Kbyte SRAM bank.
- The SAM7S256 embeds a high-speed 64-Kbyte SRAM bank.
- The SAM7S128 embeds a high-speed 32-Kbyte SRAM bank.
- The SAM7S64 embeds a high-speed 16-Kbyte SRAM bank.
- The SAM7S321 embeds a high-speed 8-Kbyte SRAM bank.
- The SAM7S32 embeds a high-speed 8-Kbyte SRAM bank.
- The SAM7S161 embeds a high-speed 4-Kbyte SRAM bank.
- The SAM7S16 embeds a high-speed 4-Kbyte SRAM bank

After reset and until the Remap Command is performed, the SRAM is only accessible at address 0x0020 0000. After Remap, the SRAM also becomes available at address 0x0.

#### 8.7.2 Internal ROM

The SAM7S Series embeds an Internal ROM. The ROM contains the FFPI and the SAM-BA program.

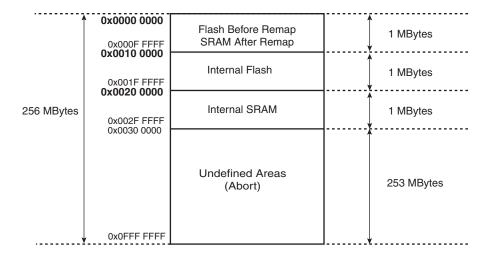
The internal ROM is not mapped by default.

#### 8.7.3 Internal Flash

- The SAM7S512 features two contiguous banks (dual plane) of 256 Kbytes of Flash.
- The SAM7S256 features one bank (single plane) of 256 Kbytes of Flash.
- The SAM7S128 features one bank (single plane) of 128 Kbytes of Flash.
- The SAM7S64 features one bank (single plane) of 64 Kbytes of Flash.
- The SAM7S321/32 features one bank (single plane) of 32 Kbytes of Flash.
- The SAM7S161/16 features one bank (single plane) of 16 Kbytes of Flash.

At any time, the Flash is mapped to address 0x0010 0000. It is also accessible at address 0x0 after the reset and before the Remap Command.

Figure 8-2. Internal Memory Mapping







#### 8.8 Embedded Flash

#### 8.8.1 Flash Overview

- The Flash of the SAM7S512 is organized in two banks (dual plane) of 1024 pages of 256 bytes. The 524,288 bytes are organized in 32-bit words.
- The Flash of the SAM7S256 is organized in 1024 pages (single plane) of 256 bytes. The 262,144 bytes are organized in 32-bit words.
- The Flash of the SAM7S128 is organized in 512 pages (single plane) of 256 bytes. The 131,072 bytes are organized in 32-bit words.
- The Flash of the SAM7S64 is organized in 512 pages (single plane) of 128 bytes. The 65,536 bytes are organized in 32-bit words.
- The Flash of the SAM7S321/32 is organized in 256 pages (single plane) of 128 bytes. The 32,768 bytes are organized in 32-bit words.
- The Flash of the SAM7S161/16 is organized in 256 pages (single plane) of 64 bytes. The 16,384 bytes are organized in 32-bit words.
- The Flash of the SAM7S512/256/128 contains a 256-byte write buffer, accessible through a 32-bit interface.
- The Flash of the SAM7S64/321/32/161/16 contains a 128-byte write buffer, accessible through a 32-bit interface.

The Flash benefits from the integration of a power reset cell and from the brownout detector. This prevents code corruption during power supply changes, even in the worst conditions.

When Flash is not used (read or write access), it is automatically placed into standby mode.

#### 8.8.2 Embedded Flash Controller

The Embedded Flash Controller (EFC) manages accesses performed by the masters of the system. It enables reading the Flash and writing the write buffer. It also contains a User Interface, mapped within the Memory Controller on the APB. The User Interface allows:

- programming of the access parameters of the Flash (number of wait states, timings, etc.)
- starting commands such as full erase, page erase, page program, NVM bit set, NVM bit clear, etc.
- getting the end status of the last command
- · getting error status
- programming interrupts on the end of the last commands or on errors

The Embedded Flash Controller also provides a dual 32-bit prefetch buffer that optimizes 16-bit access to the Flash. This is particularly efficient when the processor is running in Thumb mode.

Two EFCs are embedded in the SAM7S512 to control each bank of 256 Kbytes. Dual plane organization allows concurrent Read and Program. Read from one memory plane may be performed even while program or erase functions are being executed in the other memory plane.

One EFC is embedded in the SAM7S256/128/64/32/321/161/16 to control the single plane 256/128/64/32/16 Kbytes.

#### 8.8.3 Lock Regions

#### 8.8.3.1 SAM7S512

Two Embedded Flash Controllers each manage 16 lock bits to protect 16 regions of the flash against inadvertent flash erasing or programming commands. The SAM7S512 contains 32 lock regions and each lock region contains 64 pages of 256 bytes. Each lock region has a size of 16 Kbytes.

If a locked-region's erase or program command occurs, the command is aborted and the LOCKE bit in the MC\_FSR register rises and the interrupt line rises if the LOCKE bit has been written at 1 in the MC\_FMR register.

The 16 NVM bits (or 32 NVM bits) are software programmable through the corresponding EFC User Interface. The command "Set Lock Bit" enables the protection. The command "Clear Lock Bit" unlocks the lock region.

Asserting the ERASE pin clears the lock bits, thus unlocking the entire Flash.

#### 8.8.3.2 SAM7S256

The Embedded Flash Controller manages 16 lock bits to protect 16 regions of the flash against inadvertent flash erasing or programming commands. The SAM7S256 contains 16 lock regions and each lock region contains 64 pages of 256 bytes. Each lock region has a size of 16 Kbytes.

If a locked-region's erase or program command occurs, the command is aborted and the LOCKE bit in the MC\_FSR register rises and the interrupt line rises if the LOCKE bit has been written at 1 in the MC\_FMR register.

The 16 NVM bits are software programmable through the EFC User Interface. The command "Set Lock Bit" enables the protection. The command "Clear Lock Bit" unlocks the lock region.

Asserting the ERASE pin clears the lock bits, thus unlocking the entire Flash.

#### 8.8.3.3 SAM7S128

The Embedded Flash Controller manages 8 lock bits to protect 8 regions of the flash against inadvertent flash erasing or programming commands. The SAM7S128 contains 8 lock regions and each lock region contains 64 pages of 256 bytes. Each lock region has a size of 16 Kbytes.

If a locked-region's erase or program command occurs, the command is aborted and the LOCKE bit in the MC\_FSR register rises and the interrupt line rises if the LOCKE bit has been written at 1 in the MC\_FMR register.

The 8 NVM bits are software programmable through the EFC User Interface. The command "Set Lock Bit" enables the protection. The command "Clear Lock Bit" unlocks the lock region.

Asserting the ERASE pin clears the lock bits, thus unlocking the entire Flash.

#### 8.8.3.4 SAM7S64

The Embedded Flash Controller manages 16 lock bits to protect 16 regions of the flash against inadvertent flash erasing or programming commands. The SAM7S64 contains 16 lock regions and each lock region contains 32 pages of 128 bytes. Each lock region has a size of 4 Kbytes.

If a locked-region's erase or program command occurs, the command is aborted and the LOCKE bit in the MC\_FSR register rises and the interrupt line rises if the LOCKE bit has been written at 1 in the MC\_FMR register.





The 16 NVM bits are software programmable through the EFC User Interface. The command "Set Lock Bit" enables the protection. The command "Clear Lock Bit" unlocks the lock region.

Asserting the ERASE pin clears the lock bits, thus unlocking the entire Flash.

#### 8.8.3.5 SAM7S321/32

The Embedded Flash Controller manages 8 lock bits to protect 8 regions of the flash against inadvertent flash erasing or programming commands. The SAM7S321/32 contains 8 lock regions and each lock region contains 32 pages of 128 bytes. Each lock region has a size of 4 Kbytes.

If a locked-region's erase or program command occurs, the command is aborted and the LOCKE bit in the MC\_FSR register rises and the interrupt line rises if the LOCKE bit has been written at 1 in the MC\_FMR register.

The 8 NVM bits are software programmable through the EFC User Interface. The command "Set Lock Bit" enables the protection. The command "Clear Lock Bit" unlocks the lock region.

Asserting the ERASE pin clears the lock bits, thus unlocking the entire Flash.

#### 8.8.3.6 SAM7S161/16

The Embedded Flash Controller manages 8 lock bits to protect 8 regions of the flash against inadvertent flash erasing or programming commands. The SAM7S161/16 contains 8 lock regions and each lock region contains 32 pages of 64 bytes. Each lock region has a size of 2 Kbytes.

If a locked-region's erase or program command occurs, the command is aborted and the LOCKE bit in the MC\_FSR register rises and the interrupt line rises if the LOCKE bit has been written at 1 in the MC\_FMR register.

The 8 NVM bits are software programmable through the EFC User Interface. The command "Set Lock Bit" enables the protection. The command "Clear Lock Bit" unlocks the lock region.

Asserting the ERASE pin clears the lock bits, thus unlocking the entire Flash.

Table 8-1 summarizes the configuration of the eight devices.

 Table 8-1.
 Flash Configuration Summary

Device	Number of Lock Bits	Number of Pages in the Lock Region	Page Size
SAM7S512	32	64	256 bytes
SAM7S256	16	64	256 bytes
SAM7S128	8	64	256 bytes
SAM7S64	16	32	128 bytes
SAM7S321/32	8	32	128 bytes
SAM7S161/16	8	32	64 bytes

#### 8.8.4 Security Bit Feature

24

The SAM7S Series features a security bit, based on a specific NVM Bit. When the security is enabled, any access to the Flash, either through the ICE interface or through the Fast Flash Programming Interface, is forbidden. This ensures the confidentiality of the code programmed in the Flash.

# **SAM7S Series Summary**

This security bit can only be enabled, through the Command "Set Security Bit" of the EFC User Interface. Disabling the security bit can only be achieved by asserting the ERASE pin at 1, and after a full flash erase is performed. When the security bit is deactivated, all accesses to the flash are permitted.

It is important to note that the assertion of the ERASE pin should always be longer than 50 ms.

As the ERASE pin integrates a permanent pull-down, it can be left unconnected during normal operation. However, it is safer to connect it directly to GND for the final application.

#### 8.8.5 Non-volatile Brownout Detector Control

Two general purpose NVM (GPNVM) bits are used for controlling the brownout detector (BOD), so that even after a power loss, the brownout detector operations remain in their state.

These two GPNVM bits can be cleared or set respectively through the commands "Clear General-purpose NVM Bit" and "Set General-purpose NVM Bit" of the EFC User Interface.

- GPNVM Bit 0 is used as a brownout detector enable bit. Setting the GPNVM Bit 0 enables
  the BOD, clearing it disables the BOD. Asserting ERASE clears the GPNVM Bit 0 and thus
  disables the brownout detector by default.
- The GPNVM Bit 1 is used as a brownout reset enable signal for the reset controller. Setting
  the GPNVM Bit 1 enables the brownout reset when a brownout is detected, Clearing the
  GPNVM Bit 1 disables the brownout reset. Asserting ERASE disables the brownout reset by
  default.

#### 8.8.6 Calibration Bits

Eight NVM bits are used to calibrate the brownout detector and the voltage regulator. These bits are factory configured and cannot be changed by the user. The ERASE pin has no effect on the calibration bits.

## 8.9 Fast Flash Programming Interface

The Fast Flash Programming Interface allows programming the device through either a serial JTAG interface or through a multiplexed fully-handshaked parallel port. It allows gang-programming with market-standard industrial programmers.

The FFPI supports read, page program, page erase, full erase, lock, unlock and protect commands.

The Fast Flash Programming Interface is enabled and the Fast Programming Mode is entered when the TST pin and the PA0 and PA1 pins are all tied high and PA2 is tied low.

### 8.10 SAM-BA Boot Assistant

The SAM-BA® Boot Recovery restores the SAM-BA Boot in the first two sectors of the on-chip Flash memory. The SAM-BA Boot recovery is performed when the TST pin and the PA0, PA1 and PA2 pins are all tied high for 10 seconds. Then, a power cycle of the board is mandatory. The SAM-BA Boot Assistant is a default Boot Program that provides an easy way to program in situ the on-chip Flash memory.

The SAM-BA Boot Assistant supports serial communication through the DBGU or through the USB Device Port. (The SAM7S32/16 have no USB Device Port.)

 Communication through the DBGU supports a wide range of crystals from 3 to 20 MHz via software auto-detection.





• Communication through the USB Device Port is limited to an 18.432 MHz crystal. ( The SAM-BA Boot provides an interface with SAM-BA Graphic User Interface (GUI).

## 9. System Controller

The System Controller manages all vital blocks of the microcontroller: interrupts, clocks, power, time, debug and reset.

The System Controller peripherals are all mapped to the highest 4 Kbytes of address space, between addresses 0xFFFF F000 and 0xFFFF FFFF.

Figure 9-1 on page 27 and Figure 9-2 on page 28 show the product specific System Controller Block Diagrams.

Figure 8-1 on page 20 shows the mapping of the User Interface of the System Controller peripherals. Note that the memory controller configuration user interface is also mapped within this address space.

System Controller Block Diagram (SAM7S512/256/128/64/321/161) dbgu\_irq pmc\_irq rstc\_irq power\_on\_reset force\_ntrst MCK periph\_nreset dbgu\_irq Debug → force\_ntrst Unit dbgu\_rxd → dbgu\_txd security\_bit Periodic MCK Interval → pit\_irq periph\_nreset Timer flash\_poe SLCK-Real-Time → rtt\_irq Timer flash\_wrdis periph\_nreset cal SLCK Watchdog gpnvm[0..1] wdt\_irq Timer proc\_nreset wdt\_fault WDRPROC gpnvm[0] MCK bod\_rst\_en ➤ flash\_wrdis BOD proc\_nreset power\_on\_reset → periph\_nreset Reset ► jtag\_nreset Controller proc\_nreset Voltage **POR** ► flash\_poe Regulator standby Mode Controller NRST \_\_\_\_ → rstc\_irq cal SLCK SLCK RCOSC periph\_clk[2..14] UDPCK → pck[0-2] periph\_clk[11] XIN OSC MAINCK Management periph\_nreset → PCK XOUT Controller → UDPCK periph\_irq[11] → MCK usb\_suspend PLLRC -PLL PLLCK → pmc\_irq → idle periph\_nreset periph\_clk[4..14] usb\_suspend periph\_nreset periph\_nreset periph\_irq{2] periph\_clk[2] → irq0-irq1 periph\_irq[4..14] PIO dbgu\_rxd → fiq Controller → dbgu\_txd out enable

Figure 9-1.





Figure 9-2. System Controller Block Diagram (SAM7S32/16) ARM7TDI Controller proc\_nreset periph\_irq[2..14] -PCK debug pit\_irq \_\_ rtt\_irq \_\_ wdt ira dbgu\_irq power\_on\_reset force ntrst MCK dbgu\_irq periph\_nreset Debug force\_ntrst Unit  $dbgu\_rxd$ dbgu\_txd security\_bit Periodic MCK debug Interval → pit\_irq periph\_nreset Timer flash\_poe SLCK Real-Time Embedde → rtt\_irq Timer Flash flash\_wrdis periph\_nreset SLCK Watchdog gpnvm[0..1] → wdt\_irq idle Timer proc\_nreset cal wdt\_fault WDRPROC gpnvm[1]gpnvm[0] MCK bod\_rst\_en Memory BOD → flash wrdis Controlle proc\_nreset power\_on\_reset periph\_nreset Reset Voltage ► jtag\_nreset Controller proc nreset POR ► flash\_poe Regulator standby Mode Voltage Controller Regulato → rstc\_irq NRST cal SLCK SLCK **RCOSC** → periph\_clk[2..14] ▶ pck[0-2] XIN Power MAINCK OSC Management → PCK XOUT Controller → MCK PLLRC -PLL PLLCK → pmc\_irq int ➤ idle periph\_nreset periph\_clk[4..14] periph\_nreset Embedde Periphera periph\_nreset → periph\_irq{2] periph\_clk[2] → irq0 periph\_irq[4..14] PIO → fiq dbgu\_rxd Controller → dbgu\_txd in PA0-PA20 out enable

# **SAM7S Series Summary**

#### 9.1 Reset Controller

The Reset Controller is based on a power-on reset cell and one brownout detector. It gives the status of the last reset, indicating whether it is a power-up reset, a software reset, a user reset, a watchdog reset or a brownout reset. In addition, it controls the internal resets and the NRST pin open-drain output. It allows to shape a signal on the NRST line, guaranteeing that the length of the pulse meets any requirement.

Note that if NRST is used as a reset output signal for external devices during power-off, the brownout detector must be activated.

#### 9.1.1 Brownout Detector and Power-on Reset

The SAM7S Series embeds a brownout detection circuit and a power-on reset cell. Both are supplied with and monitor VDDCORE. Both signals are provided to the Flash to prevent any code corruption during power-up or power-down sequences or if brownouts occur on the VDDCORE power supply.

The power-on reset cell has a limited-accuracy threshold at around 1.5V. Its output remains low during power-up until VDDCORE goes over this voltage level. This signal goes to the reset controller and allows a full re-initialization of the device.

The brownout detector monitors the VDDCORE level during operation by comparing it to a fixed trigger level. It secures system operations in the most difficult environments and prevents code corruption in case of brownout on the VDDCORE.

Only VDDCORE is monitored.

When the brownout detector is enabled and VDDCORE decreases to a value below the trigger level (Vbot-, defined as Vbot - hyst/2), the brownout output is immediately activated.

When VDDCORE increases above the trigger level (Vbot+, defined as Vbot + hyst/2), the reset is released. The brownout detector only detects a drop if the voltage on VDDCORE stays below the threshold voltage for longer than about 1µs.

The threshold voltage has a hysteresis of about 50 mV, to ensure spike free brownout detection. The typical value of the brownout detector threshold is 1.68V with an accuracy of  $\pm$  2% and is factory calibrated.

The brownout detector is low-power, as it consumes less than 20  $\mu$ A static current. However, it can be deactivated to save its static current. In this case, it consumes less than 1 $\mu$ A. The deactivation is configured through the GPNVM bit 0 of the Flash.





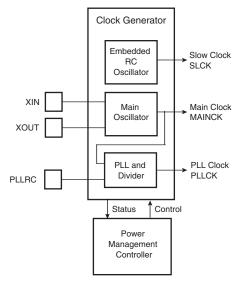
#### 9.2 Clock Generator

The Clock Generator embeds one low-power RC Oscillator, one Main Oscillator and one PLL with the following characteristics:

- RC Oscillator ranges between 22 kHz and 42 kHz
- Main Oscillator frequency ranges between 3 and 20 MHz
- · Main Oscillator can be bypassed
- PLL output ranges between 80 and 220 MHz

It provides SLCK, MAINCK and PLLCK.

Figure 9-3. Clock Generator Block Diagram



## 9.3 Power Management Controller

The Power Management Controller uses the Clock Generator outputs to provide:

- the Processor Clock PCK
- the Master Clock MCK
- the USB Clock UDPCK (not present on SAM7S32/16)
- all the peripheral clocks, independently controllable
- three programmable clock outputs

The Master Clock (MCK) is programmable from a few hundred Hz to the maximum operating frequency of the device.

The Processor Clock (PCK) switches off when entering processor idle mode, thus allowing reduced power consumption while waiting for an interrupt.

Processor ► PCK Clock Controller Master Clock Controlle Idle Mode SLCK Prescaler MAINCK PLLCK MCK 1,/2,/4,...,/64 Peripherals → periph\_clk[2..14] Clock Controller ON/OFF Programmable Clock Controller SLCK Prescaler MAINCK PLLCK → pck[0..2] 1./2./4..../64 **USB Clock Controller** usb suspend ON/OFF PLLCK → UDPCK

Figure 9-4. Power Management Controller Block Diagram

## 9.4 Advanced Interrupt Controller

- Controls the interrupt lines (nIRQ and nFIQ) of an ARM Processor
- Individually maskable and vectored interrupt sources
  - Source 0 is reserved for the Fast Interrupt Input (FIQ)
  - Source 1 is reserved for system peripherals RTT, PIT, EFC, PMC, DBGU, etc.)
  - Other sources control the peripheral interrupts or external interrupts
  - Programmable edge-triggered or level-sensitive internal sources
  - Programmable positive/negative edge-triggered or high/low level-sensitive external sources
- 8-level Priority Controller
  - Drives the normal interrupt of the processor
  - Handles priority of the interrupt sources
  - Higher priority interrupts can be served during service of lower priority interrupt
- Vectoring
  - Optimizes interrupt service routine branch and execution
  - One 32-bit vector register per interrupt source
  - Interrupt vector register reads the corresponding current interrupt vector
- Protect Mode
  - Easy debugging by preventing automatic operations
- Fast Forcing
  - Permits redirecting any interrupt source on the fast interrupt
- General Interrupt Mask
  - Provides processor synchronization on events without triggering an interrupt





## 9.5 Debug Unit

- Comprises:
  - One two-pin UART
  - One Interface for the Debug Communication Channel (DCC) support
  - One set of Chip ID Registers
  - One Interface providing ICE Access Prevention
- Two-pin UART
  - Implemented features are compatible with the USART
  - Programmable Baud Rate Generator
  - Parity, Framing and Overrun Error
  - Automatic Echo, Local Loopback and Remote Loopback Channel Modes
- Debug Communication Channel Support
  - Offers visibility of COMMRX and COMMTX signals from the ARM Processor
- Chip ID Registers
  - Identification of the device revision, sizes of the embedded memories, set of peripherals
  - Chip ID is 0x270B0A40 for AT91SAM7S512 Rev A
  - Chip ID is 0x270B0A4F for AT91SAM7S512 Rev B
  - Chip ID is 0x270D0940 for AT91SAM7S256 Rev A
  - Chip ID is 0x270B0941 for AT91SAM7S256 Rev B
  - Chip ID is 0x270B0942 for AT91SAM7S256 Rev C
  - Chip ID is 0x270C0740 for AT91SAM7S128 Rev A
  - Chip ID is 0x270A0741 for AT91SAM7S128 Rev B
  - Chip ID is 0x270A0742 for AT91SAM7S128 Rev C
  - Chip ID is 0x27090540 for AT91SAM7S64 Rev A
  - Chip ID is 0x27090543 for AT91SAM7S64 Rev B
  - Chip ID is 0x27090544 for AT91SAM7S64 Rev C
  - Chip ID is 0x27080342 for AT91SAM7S321 Rev A
  - Chip ID is 0x27080340 for AT91SAM7S32 Rev A
  - Chip ID is 0x27080341 for AT91SAM7S32 Rev B
  - Chip ID is 0x27050241 for AT9SAM7S161 Rev A
  - Chip ID is 0x27050240 for AT91SAM7S16 Rev A

Note: Refer to the errata section of the datasheet for updates on chip ID.

### 9.6 Periodic Interval Timer

• 20-bit programmable counter plus 12-bit interval counter

## 9.7 Watchdog Timer

- 12-bit key-protected Programmable Counter running on prescaled SCLK
- Provides reset or interrupt signals to the system
- Counter may be stopped while the processor is in debug state or in idle mode

# **SAM7S Series Summary**

### 9.8 Real-time Timer

- 32-bit free-running counter with alarm running on prescaled SCLK
- Programmable 16-bit prescaler for SLCK accuracy compensation

#### 9.9 PIO Controller

- One PIO Controller, controlling 32 I/O lines (21 for SAM7S32/16)
- Fully programmable through set/clear registers
- Multiplexing of two peripheral functions per I/O line
- For each I/O line (whether assigned to a peripheral or used as general-purpose I/O)
  - Input change interrupt
  - Half a clock period glitch filter
  - Multi-drive option enables driving in open drain
  - Programmable pull-up on each I/O line
  - Pin data status register, supplies visibility of the level on the pin at any time
- Synchronous output, provides Set and Clear of several I/O lines in a single write

## 9.10 Voltage Regulator Controller

The aim of this controller is to select the Power Mode of the Voltage Regulator between Normal Mode (bit 0 is cleared) or Standby Mode (bit 0 is set).





## 10. Peripherals

#### 10.1 User Interface

The User Peripherals are mapped in the 256 MBytes of address space between 0xF000 0000 and 0xFFFF EFFF. Each peripheral is allocated 16 Kbytes of address space.

A complete memory map is provided in Figure 8-1 on page 20.

## 10.2 Peripheral Identifiers

The SAM7S Series embeds a wide range of peripherals. Table 10-1 defines the Peripheral Identifiers of the SAM7S512/256/128/64/321/161. Table 10-2 defines the Peripheral Identifiers of the SAM7S32/16. A peripheral identifier is required for the control of the peripheral interrupt with the Advanced Interrupt Controller and for the control of the peripheral clock with the Power Management Controller.

**Table 10-1.** Peripheral Identifiers (SAM7S512/256/128/64/321/161)

Peripheral	Peripheral	Peripheral	External
ID	Mnemonic	Name	Interrupt
0	AIC	Advanced Interrupt Controller	FIQ
1	SYSC <sup>(1)</sup>	System	
2	PIOA	Parallel I/O Controller A	
3	Reserved		
4	ADC <sup>(1)</sup>	Analog-to Digital Converter	
5	SPI	Serial Peripheral Interface	
6	US0	USART 0	
7	US1	USART 1	
8	SSC	Synchronous Serial Controller	
9	TWI	Two-wire Interface	
10	PWMC	PWM Controller	
11	UDP	USB Device Port	
12	TC0	Timer/Counter 0	
13	TC1	Timer/Counter 1	
14	TC2	Timer/Counter 2	
15 - 29	Reserved		
30	AIC	Advanced Interrupt Controller	IRQ0
31	AIC	Advanced Interrupt Controller	IRQ1

Note: 1. Setting SYSC and ADC bits in the clock set/clear registers of the PMC has no effect. The System Controller is continuously clocked. The ADC clock is automatically started for the first conversion. In Sleep Mode the ADC clock is automatically stopped after each conversion.

**Table 10-2.** Peripheral Identifiers (SAM7S32/16)

Peripheral	Peripheral	Peripheral	External
ID	Mnemonic	Name	Interrupt
0	AIC	Advanced Interrupt Controller	FIQ
1	SYSC <sup>(1)</sup>	System	
2	PIOA	Parallel I/O Controller A	
3	Reserved		
4	ADC <sup>(1)</sup>	Analog-to Digital Converter	
5	SPI	Serial Peripheral Interface	
6	US	USART	
7	Reserved		
8	SSC	Synchronous Serial Controller	
9	TWI	Two-wire Interface	
10	PWMC	PWM Controller	
11	Reserved		
12	TC0	Timer/Counter 0	
13	TC1	Timer/Counter 1	
14	TC2	Timer/Counter 2	
15 - 29	Reserved		
30	AIC	Advanced Interrupt Controller	IRQ0
31	Reserved		
Note: 1. Setting SYSC and ADC bits in the clock set/clear registers of the PMC has no effect. The Sys			

Setting SYSC and ADC bits in the clock set/clear registers of the PMC has no effect. The System Controller is continuously clocked. The ADC clock is automatically started for the first conversion. In Sleep Mode the ADC clock is automatically stopped after each conversion.

## 10.3 Peripheral Multiplexing on PIO Lines

The SAM7S Series features one PIO controller, PIOA, that multiplexes the I/O lines of the peripheral set.

PIO Controller A controls 32 lines (21 lines for SAM7S32/16). Each line can be assigned to one of two peripheral functions, A or B. Some of them can also be multiplexed with the analog inputs of the ADC Controller.

Table 10-3, "Multiplexing on PIO Controller A (SAM7S512/256/128/64/321/161)," on page 36 and Table 10-4, "Multiplexing on PIO Controller A (SAM7S32/16)," on page 37 define how the I/O lines of the peripherals A, B or the analog inputs are multiplexed on the PIO Controller A. The two columns "Function" and "Comments" have been inserted for the user's own comments; they may be used to track how pins are defined in an application.

Note that some peripheral functions that are output only may be duplicated in the table.

All pins reset in their Parallel I/O lines function are configured as input with the programmable pull-up enabled, so that the device is maintained in a static state as soon as a reset is detected.





## 10.4 PIO Controller A Multiplexing

**Table 10-3.** Multiplexing on PIO Controller A (SAM7S512/256/128/64/321/161)

PIO Controller A		Application Usage			
I/O Line	Peripheral A	Peripheral B	Comments	Function	Comments
PA0	PWM0	TIOA0	High-Drive		
PA1	PWM1	TIOB0	High-Drive		
PA2	PWM2	SCK0	High-Drive		
PA3	TWD	NPCS3	High-Drive		
PA4	TWCK	TCLK0			
PA5	RXD0	NPCS3			
PA6	TXD0	PCK0			
PA7	RTS0	PWM3			
PA8	CTS0	ADTRG			
PA9	DRXD	NPCS1			
PA10	DTXD	NPCS2			
PA11	NPCS0	PWM0			
PA12	MISO	PWM1			
PA13	MOSI	PWM2			
PA14	SPCK	PWM3			
PA15	TF	TIOA1			
PA16	TK	TIOB1			
PA17	TD	PCK1	AD0		
PA18	RD	PCK2	AD1		
PA19	RK	FIQ	AD2		
PA20	RF	IRQ0	AD3		
PA21	RXD1	PCK1			
PA22	TXD1	NPCS3			
PA23	SCK1	PWM0			
PA24	RTS1	PWM1			
PA25	CTS1	PWM2			
PA26	DCD1	TIOA2			
PA27	DTR1	TIOB2			
PA28	DSR1	TCLK1			
PA29	RI1	TCLK2			
PA30	IRQ1	NPCS2			
PA31	NPCS1	PCK2			

Table 10-4. Multiplexing on PIO Controller A (SAM7S32/16)

	PIO Controller A			Application U	sage	
I/O Line	Peripheral A	Peripheral B	Comments	Function	Comments	
PA0	PWM0	TIOA0	High-Drive			
PA1	PWM1	TIOB0	High-Drive			
PA2	PWM2	SCK0	High-Drive			
PA3	TWD	NPCS3	High-Drive			
PA4	TWCK	TCLK0				
PA5	RXD0	NPCS3				
PA6	TXD0	PCK0				
PA7	RTS0	PWM3				
PA8	CTS0	ADTRG				
PA9	DRXD	NPCS1				
PA10	DTXD	NPCS2				
PA11	NPCS0	PWM0				
PA12	MISO	PWM1				
PA13	MOSI	PWM2				
PA14	SPCK	PWM3				
PA15	TF	TIOA1				
PA16	TK	TIOB1				
PA17	TD	PCK1	AD0			
PA18	RD	PCK2	AD1			
PA19	RK	FIQ	AD2			
PA20	RF	IRQ0	AD3			





## 10.5 Serial Peripheral Interface

- · Supports communication with external serial devices
  - Four chip selects with external decoder allow communication with up to 15 peripherals
  - Serial memories, such as DataFlash® and 3-wire EEPROMs
  - Serial peripherals, such as ADCs, DACs, LCD Controllers, CAN Controllers and Sensors
  - External co-processors
- Master or slave serial peripheral bus interface
  - 8- to 16-bit programmable data length per chip select
  - Programmable phase and polarity per chip select
  - Programmable transfer delays between consecutive transfers and between clock and data per chip select
  - Programmable delay between consecutive transfers
  - Selectable mode fault detection
  - Maximum frequency at up to Master Clock

### 10.6 Two-wire Interface

- Master Mode only (SAM7S512/256/128/64/321/32)
- Master, Multi-Master and Slave Mode support (SAM7S161/16)
- General Call supported in Slave Mode (SAM7S161/16)
- Compatibility with I<sup>2</sup>C compatible devices (refer to the TWI sections of the datasheet)
- One, two or three bytes internal address registers for easy Serial Memory access
- 7-bit or 10-bit slave addressing
- Sequential read/write operations

### **10.7 USART**

- Programmable Baud Rate Generator
- 5- to 9-bit full-duplex synchronous or asynchronous serial communications
  - 1, 1.5 or 2 stop bits in Asynchronous Mode
  - 1 or 2 stop bits in Synchronous Mode
  - Parity generation and error detection
  - Framing error detection, overrun error detection
  - MSB or LSB first
  - Optional break generation and detection
  - By 8 or by 16 over-sampling receiver frequency
  - Hardware handshaking RTS CTS
  - Modem Signals Management DTR-DSR-DCD-RI on USART1 (not present on SAM7S32/16)
  - Receiver time-out and transmitter timeguard
  - Multi-drop Mode with address generation and detection
- RS485 with driver control signal

- ISO7816, T = 0 or T = 1 Protocols for interfacing with smart cards
  - NACK handling, error counter with repetition and iteration limit
- IrDA modulation and demodulation
  - Communication at up to 115.2 Kbps
- Test Modes
  - Remote Loopback, Local Loopback, Automatic Echo

## 10.8 Serial Synchronous Controller

- Provides serial synchronous communication links used in audio and telecom applications
- Contains an independent receiver and transmitter and a common clock divider
- Offers a configurable frame sync and data length
- Receiver and transmitter can be programmed to start automatically or on detection of different event on the frame sync signal
- Receiver and transmitter include a data signal, a clock signal and a frame synchronization signal

### 10.9 Timer Counter

- Three 16-bit Timer Counter Channels
  - Two output compare or one input capture per channel (except for SAM7S32/16 which have only two channels connected to the PIO)
- Wide range of functions including:
  - Frequency measurement
  - Event counting
  - Interval measurement
  - Pulse generation
  - Delay timing
  - Pulse Width Modulation
  - Up/down capabilities
- Each channel is user-configurable and contains:
  - Three external clock inputs (The SAM7S32/16 have one)
  - Five internal clock inputs, as defined in Table 10-5

 Table 10-5.
 Timer Counter Clocks Assignment

TC Clock Input	Clock
TIMER_CLOCK1	MCK/2
TIMER_CLOCK2	MCK/8
TIMER_CLOCK3	MCK/32
TIMER_CLOCK4	MCK/128
TIMER_CLOCK5	MCK/1024

- Two multi-purpose input/output signals
- Two global registers that act on all three TC channels





### 10.10 PWM Controller

- Four channels, one 16-bit counter per channel
- · Common clock generator, providing thirteen different clocks
  - One Modulo n counter providing eleven clocks
  - Two independent linear dividers working on modulo n counter outputs
- Independent channel programming
  - Independent enable/disable commands
  - Independent clock selection
  - Independent period and duty cycle, with double buffering
  - Programmable selection of the output waveform polarity
  - Programmable center or left aligned output waveform

## 10.11 USB Device Port (Does not pertain to SAM7S32/16)

- USB V2.0 full-speed compliant, 12 Mbits per second.
- Embedded USB V2.0 full-speed transceiver
- Embedded 328-byte dual-port RAM for endpoints
- · Four endpoints
  - Endpoint 0: 8 bytes
  - Endpoint 1 and 2: 64 bytes ping-pong
  - Endpoint 3: 64 bytes
  - Ping-pong Mode (two memory banks) for isochronous and bulk endpoints
- Suspend/resume logic

## 10.12 Analog-to-digital Converter

- 8-channel ADC
- 10-bit 384 Ksamples/sec. or 8-bit 583 Ksamples/sec. Successive Approximation Register ADC
- ±2 LSB Integral Non Linearity, ±1 LSB Differential Non Linearity
- Integrated 8-to-1 multiplexer, offering eight independent 3.3V analog inputs
- External voltage reference for better accuracy on low voltage inputs
- · Individual enable and disable of each channel
- Multiple trigger source
  - Hardware or software trigger
  - External trigger pin
  - Timer Counter 0 to 2 outputs TIOA0 to TIOA2 trigger
- Sleep Mode and conversion sequencer
  - Automatic wakeup on trigger and back to sleep mode after conversions of all enabled channels
- Four of eight analog inputs shared with digital signals

## 11. Package Drawings

The SAM7S series devices are available in LQFP and QFN package types.

## 11.1 LQFP Packages

Figure 11-1. 48-and 64-lead LQFP Package Drawing

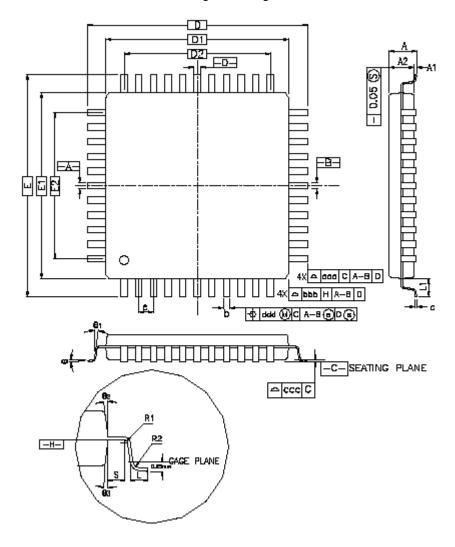




Table 11-1. 48-lead LQFP Package Dimensions (in mm)

		Millimeter			Inch	
Symbol	Min	Nom	Max	Min	Nom	Max
А	_	_	1.60	_	_	0.063
A1	0.05	_	0.15	0.002	_	0.006
A2	1.35	1.40	1.45	0.053	0.055	0.057
D		9.00 BSC			0.354 BSC	
D1		7.00 BSC			0.276 BSC	
Е		9.00 BSC			0.354 BSC	
E1		7.00 BSC			0.276 BSC	
R2	0.08	_	0.20	0.003	_	0.008
R1	0.08	_	_	0.003	_	-
q	0°	3.5°	7°	0°	3.5°	7°
$\theta_1$	0°	_	_	0°	_	_
$\theta_2$	11°	12°	13°	11°	12°	13°
$\theta_3$	11°	12°	13°	11°	12°	13°
С	0.09	_	0.20	0.004	_	800.0
L	0.45	0.60	0.75	0.018	0.024	0.030
L1		1.00 REF		0.039 REF		
S	0.20	_	_	0.008	_	_
b	0.17	0.20	0.27	0.007	0.008	0.011
е		0.50 BSC.		0.020 BSC.		
D2		5.50		0.217		
E2	5.50			0.217		
		Tolerance	es of Form and	d Position		
aaa	0.20			0.008		
bbb	0.20			0.008		
ccc		0.08		0.003		
ddd		0.08			0.003	

Table 11-2. 64-lead LQFP Package Dimensions (in mm)

Crossele ed		Millimeter			Inch	
Symbol	Min	Nom	Max	Min	Nom	Max
Α	_	_	1.60	_	_	0.063
A1	0.05	_	0.15	0.002	_	0.006
A2	1.35	1.40	1.45	0.053	0.055	0.057
D		12.00 BSC			0.472 BSC	I
D1		10.00 BSC			0.383 BSC	
Е		12.00 BSC			0.472 BSC	
E1		10.00 BSC			0.383 BSC	
R2	0.08	_	0.20	0.003	_	0.008
R1	0.08	_	-	0.003	_	_
q	0°	3.5°	7°	0°	3.5°	7°
$\theta_1$	0°	_	_	0°	_	_
$\theta_2$	11°	12°	13°	11°	12°	13°
$\theta_3$	11°	12°	13°	11°	12°	13°
С	0.09	_	0.20	0.004	_	0.008
L	0.45	0.60	0.75	0.018	0.024	0.030
L1		1.00 REF			0.039 REF	
S	0.20	_	-	0.008	_	_
b	0.17	0.20	0.27	0.007	0.008	0.011
е		0.50 BSC.		0.020 BSC.		
D2		7.50			0.285	
E2	7.50			0.285		
	1	Tolerance	es of Form an	d Position		
aaa	0.20			0.008		
bbb	0.20			0.008		
ccc		0.08			0.003	
ddd		0.08			0.003	





## 11.2 QFN Packages

Figure 11-2. 48-pad QFN Package

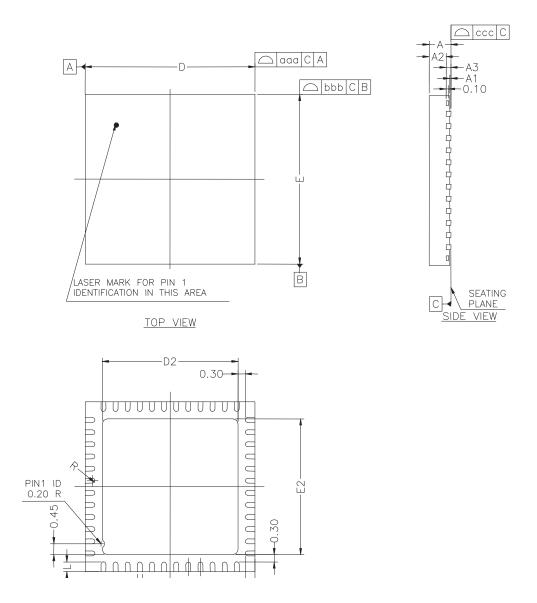


 Table 11-3.
 48-pad QFN Package Dimensions (in mm)

Cumbal		Millimeter			Inch	
Symbol	Min	Nom	Max	Min	Nom	Max
Α	-	_	090	_	-	0.035
A1	_	_	0.050	_	_	0.002
A2	_	0.65	0.70	_	0.026	0.028
A3		0.20 REF			0.008 REF	
b	0.18	0.20	0.23	0.007	0.008	0.009
D	7.00 bsc				0.276 bsc	
D2	5.45	5.60	5.75	0.215	0.220	0.226
Е		7.00 bsc		0.276 bsc		
E2	5.45	5.60	5.75	0.215	0.220	0.226
L	0.35	0.40	0.45	0.014	0.016	0.018
е		0.50 bsc			0.020 bsc	
R	0.09	_	_	0.004	_	_
		Toleranc	es of Form and	Position		
aaa	0.10				0.004	
bbb	0.10				0.004	
ccc		0.05			0.002	





Figure 11-3. 64-pad QFN Package Drawing

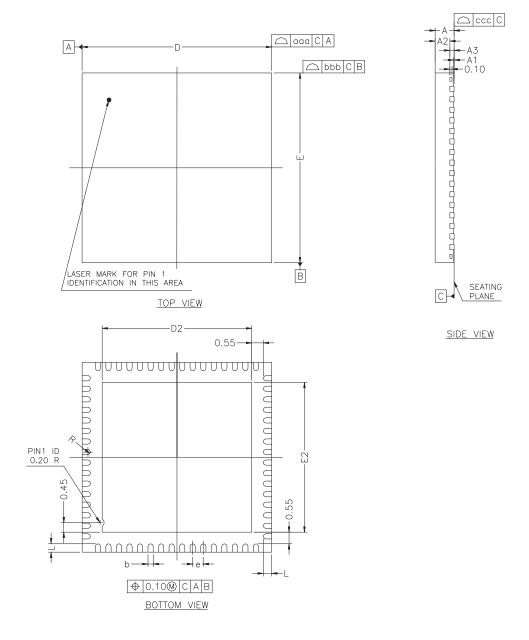


 Table 11-4.
 64-pad QFN Package Dimensions (in mm)

0 1 1		Millimeter			Inch	
Symbol	Min	Nom	Max	Min	Nom	Max
Α	_	_	090	_	_	0.035
A1	_	_	0.05	_	_	0.001
A2	_	0.65	0.70	-	0.026	0.028
A3	0.20 REF 0.008 REF					
b	0.23	0.25	0.28	0.009	0.010	0.011
D	9.00 bsc			0.354 bsc		
D2	6.95	7.10	7.25	0.274	0.280	0.285
Е		9.00 bsc		0.354 bsc		
E2	6.95	7.10	7.25	0.274	0.280	0.285
L	0.35	0.40	0.45	0.014	0.016	0.018
е		0.50 bsc			0.020 bsc	
R	0.125	_	_	0.0005	_	_
	Tolerances of Form and Position					
aaa	0.10				0.004	
bbb	0.10				0.004	
ccc		0.05			0.002	





## 12. SAM7S Ordering Information

 Table 12-1.
 SAM7S Series Ordering Information

MLR A Ordering Code	MLR B Ordering Code	MLR C Ordering Code	Package	Package Type	Temperature Operating Range
AT91SAM7S16-AU AT91SAM7S16-MU	-	_	LQFP 48 QFN 48	Green	Industrial (-40· C to 85· C)
AT91SAM7S161-AU	-	_	LQFP 64	Green	Industrial (-40· C to 85· C)
AT91SAM7S32-AU-001 AT91SAM7S32-MU	AT91SAM7S32B-AU AT91SAM7S32B-MU	_	LQFP 48 QFN 48	Green	Industrial (-40· C to 85· C)
AT91SAM7S321-AU AT91SAM7S321-MU	_	_	LQFP 64 QFN 64	Green	Industrial (-40· C to 85· C)
-	AT91SAM7S64B-AU AT91SAM7S64B-MU	AT91SAM7S64C-AU AT91SAM7S64C-MU	LQFP 64 QFN 64	Green	Industrial (-40· C to 85· C)
-	AT91SAM7S128-AU-001 AT91SAM7S128-MU	AT91SAM7S128C-AU AT91SAM7S128C-MU	LQFP 64 QFN 64	Green	Industrial (-40· C to 85· C)
-	AT91SAM7S256-AU-001 AT91SAM7S256-MU	AT91SAM7S256C-AU AT91SAM7S256C-MU	LQFP 64 QFN 64	Green	Industrial (-40· C to 85· C)
AT91SAM7S512-AU AT91SAM7S512-MU	AT91SAM7S512B-AU AT91SAM7S512B-MU	_	LQFP 64 QFN 64	Green	Industrial (-40· C to 85· C)

## **Revision History**

Doc. Rev	Comments	Change Request Ref.
6175AS	First issue - Unqualified on Intranet Corresponds to 6175A full datasheet approval loop. Qualified on Intranet.	
6175BS	Section 8. "Memories" on page 18 updated: 2 ms => 3 ms, 10 ms => 15 ms, 4 ms => 6 ms	CSR05-529
6175CS	Section 12. "SAM7S Ordering Information" AT91SAM7S321 changed in Table 12-1 on page 48	#2342
6175DS	"Features", Table 1-1, "Configuration Summary," on page 3, Section 4. "Package and Pinout" Section 12. "SAM7S Ordering Information" QFN package information added	#2444
6175ES	Section 10.11 on page 40 USB Device port, Ping-pong Mode includes Isochronous endpoints.	specs
	"Features" on page 1, and global: AT91SAM7S512 added to series. Reference to Manchester Encoder removed from USART.	
	Section 8. "Memories" Reformatted Memories, Consolidated Memory Mapping in Figure 8-1 on page 20 Section 10. "Peripherals" Reordered sub sections.	#2748
	Section 11. "Package Drawings" QFN, LQFP package drawings added.  "ice_nreset" signals changed to" power_on_reset" in System Controller block diagrams, Figure 9-1 on page 27 and Figure 9-2 on page 28.	#2832 (DBGU IP)
	Section 4. "Package and Pinout" LQFP and QFN Package Outlines replace Mechanical Overview.  Section 10.1 "User Interface", User peripherals are mapped between 0xF000 0000 and 0xFFFF EFFF.  SYSIRQ changed to SYSC in "Peripheral Identifiers" Table 10-1 and Table 10-2	rfo review
6175FS	AT91SAM7S161 and AT91SAM7S16 added to product family	BDs
	<b>Features:</b> Timer Counter, on page 2 product specific information rewritten, Table 1-1, "Configuration Summary," on page 3, footnote explains TC on AT91SAM7S32/16 has only two channels accessible via PIO, and in Section 10.9 "Timer Counter", precisions added to "compare and capture" output/input.	4208
	Section 10.6 "Two-wire Interface", updated reference to I <sup>2</sup> C compatibility, internal address registers, slave addressing, Modes for AT91SAM7S161/16	rfo review
	"One Two-wire Interface (TWI)" on page 2, updated in Features	
	Section 10.12 "Analog-to-digital Converter", updated Successive Approximation Register ADC and the INL, DNL ± values of LSB.	
	Section 8.8.3 "Lock Regions", locked-region's erase or program command updated	
	Section 9.5 "Debug Unit", Chip ID updated.	4325
	Section 6. "I/O Lines Considerations", JTAG Port Pin, Test Pin, Erase Pin, updated.	5063





Doc. Rev	Comments	Change Request Ref.		
6175GS	"Features", "Debug Unit (DBGU)" updated with "Mode for General Purpose 2-wire UART Serial Communication"			
	Section 7.4 "Peripheral DMA Controller", added list of PDC priorities.	5913		
	Section 9. "System Controller", Figure 9-1 and Figure 9-2 RTT is reset by "power_on_reset".	5224		
	Section 9.1.1 "Brownout Detector and Power-on Reset", fourth paragraph reduced.	5685		
	Section 9.5 "Debug Unit", the list; Section • "Chip ID Registers", chip IDs updated, added SAM7S32 Rev B and SAM7S64 Rev B to the list.	rfo		
	Section 12. "SAM7S Ordering Information", Updated product ordering information by MRL A and MRL B versions.			
6175HS	Section 6.2 "Test Pin", added to SAM-BA Boot recovery procedure, a power cycle of the board is mandatory.	6068		
	Section 8.10 "SAM-BA Boot Assistant", added to SAM-BA Boot recovery procedure, a power cycle of the board is mandatory.			
6175IS	Section 9.5 "Debug Unit", Chip ID Registers list updated.			
	MRL C column added to Table 12-1, "SAM7S Series Ordering Information".	7185		
6175JS	Product Series Naming Convention	rfo		
	Except for part ordering and library references, AT91 prefix dropped from most nomenclature.			
	AT91SAM7S becomes SAM7S.			
	Debug Unit:			
	"Chip ID Registers" on page 32, Chip ID is 0x270B0A4F for AT91SAM7S512 Rev B	7945		



### Headquarters

Atmel Corporation

2325 Orchard Parkway San Jose, CA 95131 USA

Tel: (+1) (408) 441-0311 Fax: (+1) (408) 487-2600

#### International

Atmel Asia Limited

Unit 01-5 & 16, 19F BEA Tower, Millennium City 5 418 Kwun Tong Road Kwun Tong, Kowloon HONG KONG

Tel: (+852) 2245-6100 Fax: (+852) 2722-1369 Atmel Munich GmbH

Business Campus Parkring 4 D-85748 Garching b. Munich GERMANY

Tel: (+49) 89-31970-0 Fax: (+49) 89-3194621 Atmel Japan

9F, Tonetsu Shinkawa Bldg. 1-24-8 Shinkawa Chuo-ku, Tokyo 104-0033 JAPAN

Tel: (81) 3-3523-3551 Fax: (81) 3-3523-7581

#### **Product Contact**

Web Site

www.atmel.com/AT91SAM

**Technical Support**AT91SAM Support
Atmel techincal support

Sales Contacts

www.atmel.com/contacts/

Literature Requests www.atmel.com/literature

Disclaimer: The information in this document is provided in connection with Atmel products. No license, express or implied, by estoppel or otherwise, to any intellectual property right is granted by this document or in connection with the sale of Atmel products. EXCEPT AS SET FORTH IN ATMEL'S TERMS AND CONDITIONS OF SALE LOCATED ON ATMEL'S WEB SITE, ATMEL ASSUMES NO LIABILITY WHATSOEVER AND DISCLAIMS ANY EXPRESS, IMPLIED OR STATUTORY WARRANTY RELATING TO ITS PRODUCTS INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTY OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, OR NON-INFRINGEMENT. IN NO EVENT SHALL ATMEL BE LIABLE FOR ANY DIRECT, INDIRECT, CONSEQUENTIAL, PUNITIVE, SPECIAL OR INCIDENTAL DAMAGES (INCLUDING, WITHOUT LIMITATION, DAMAGES FOR LOSS OF PROFITS, BUSINESS INTERRUPTION, OR LOSS OF INFORMATION) ARISING OUT OF THE USE OR INABILITY TO USE THIS DOCUMENT, EVEN IF ATMEL HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES. Atmel makes no representations or warranties with respect to the accuracy or completeness of the contents of this document and reserves the right to make changes to specifications and product descriptions at any time without notice. Atmel does not make any commitment to update the information contained herein. Unless specifically provided otherwise, Atmel products are not suitable for, and shall not be used in, automotive applications. Atmel's products are not intended, authorized, or warranted for use as components in applications intended to support or sustain life.



© 2011 Atmel Corporation. All rights reserved. Atmel<sup>®</sup>, Atmel logo and combinations thereof, DataFlash<sup>®</sup>, SAM-BA<sup>®</sup> and others are registered trademarks or trademarks of Atmel Corporation or its subsidiaries. ARM<sup>®</sup>, the ARM Powered<sup>®</sup> logo, ARM7TDMI<sup>®</sup>, Thumb<sup>®</sup>,nd others are registered trademarks or trademarks of ARM Limited. Other terms and product names may be the trademarks of others.